

# Regularity of topological and metric entropy of hyperbolic flows.

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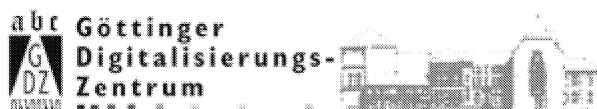
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# Regularity of topological and metric entropy of hyperbolic flows <sup>★</sup>

Gonzalo Contreras <sup>★★</sup>

IMPA, Estrada Dona Castorina, 110, 22460 Rio de Janeiro, Brazil

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## Introduction

Let  $M$  be a compact smooth manifold and let  $\mathcal{X}^r(M)$  be the Banach space of  $C^r$  vector fields on  $M$  endowed with the topology of uniform  $C^r$  convergence on compact subsets. For  $X \in \mathcal{X}^r(M)$  let  $h_{\text{top}}(X)$  be the topological entropy of  $X$ . Misiurewicz [18] proved that, for general  $C^r$  flows on  $M^n$ ,  $r < \infty$  and  $n \leq 3$ ,  $h_{\text{top}}$  need not be continuous. Yomdin and Newhouse [19, 23] proved that  $h_{\text{top}}: \mathcal{X}^\infty(M^n) \rightarrow \mathbb{R}$  is upper-semicontinuous. Katok proved that for 3-manifolds  $h_{\text{top}}: \mathcal{X}^\infty(M^3) \rightarrow \mathbb{R}$  is lower semi-continuous. By combining these two results, one sees that  $h_{\text{top}}: \mathcal{X}^\infty(M^3) \rightarrow \mathbb{R}$  is continuous. See [8] for a survey of regularity results for the topological entropy for general flows.

Let  $A$  be a hyperbolic basic set of  $X \in \mathcal{X}^r(M)$ , i.e. a compact hyperbolic transitive and isolated set. Isolated means that there exists a compact neighbourhood  $U$  of  $A$  such that  $A$  is the maximal  $X$ -invariant set of  $U$ , i.e., the set of points whose  $X$ -orbit is contained in  $U$ . By the standard theory of hyperbolic sets there exists a neighbourhood  $\mathcal{U}$  of  $X$  in  $\mathcal{X}^r(M)$  such that if  $Y \in \mathcal{U}$  then the maximal  $Y$ -invariant set of  $U$ , that we shall denote  $A_Y$ , is a hyperbolic basic set and  $X|_A$  and  $Y|_{A_Y}$  are topologically equivalent.

Our objective is to study the regularity of the entropies of  $Y|_{A_Y}$  arising from variational principles, as functions of  $Y \in \mathcal{U}$ . We begin by considering the topological entropy  $h_{\text{top}}(Y|_{A_Y})$ .

**Theorem A.** *The function  $\mathcal{U} \ni Y \rightarrow h_{\text{top}}(Y|_{A_Y}) \in \mathbb{R}$  is  $C^r$ .*

For  $r=1$  and  $A=M$  this result was proved by Katok et al. [8]. In [9] Katok et al. proved the theorem above losing one degree of differentiability. To obtain the full regularity of  $h_{\text{top}}(Y|_{A_Y})$  we use the techniques of Mañé in [15].

When  $A$  is an attractor of  $X$  (i.e. the  $\omega$ -limit set of every  $x$  nearby  $A$  is contained in  $A$ ) then  $A_Y$  is an attractor of  $Y$  for every  $Y \in \mathcal{U}$ . The set  $W^s(A_Y)$  of points  $x \in M$  whose  $\omega$ -limit set under  $Y$  is contained in  $A_Y$  (called the *basin*

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<sup>★★</sup> Current address: Matemática, PUC-Rio., R. Marquês de São Vicente 225, 22453 Rio de Janeiro, Brazil

of  $\mathcal{A}_Y$ ) is then open and there exists a unique  $Y$ -invariant probability  $\mu_Y$  (called the Bowen-Ruelle-Sinai measure) on the Borel  $\sigma$ -algebra of  $\mathcal{A}_Y$  such that for almost every  $p \in W^s(\mathcal{A}_Y)$  (with respect to the Lebesgue measure on  $M$ ), if the forward  $Y$ -orbit of  $p$  is  $x: [0, +\infty[ \rightarrow M$ , then

$$\int \varphi d\mu_Y = \lim_{T \rightarrow +\infty} \frac{1}{T} \int_0^T \varphi(x(t)) dt$$

for every continuous  $\varphi: M \rightarrow \mathbb{R}$ . Let  $h_{\mu_Y}(Y|_{\mathcal{A}_Y})$  be its metric entropy.

**Theorem B.** *The function  $\mathcal{U} \ni Y \rightarrow h_{\mu_Y}(Y|_{\mathcal{A}_Y})$  is  $C^{r-2}$ .*

It is interesting to apply this result to the geodesic flow of Riemannian manifolds with negative curvature. Given a compact boundaryless manifold  $M$  denote  $R^r(M)$  the Banach manifolds of  $C^r$  Riemannian structures  $g: TM \times TM \rightarrow \mathbb{R}$  and, if  $g \in R^r(M)$  let  $h(g)$  denote the entropy of the geodesic flow of  $g$  with respect to the Liouville measure. Let  $A^r(M)$  be the (open) set of metrics  $g \in R^r(M)$  whose geodesic flow is Anosov (in particular, metrics with negative curvature). Then the geodesic flow is generated by a  $C^{r-1}$  vector field for which the whole unit tangent bundle is a hyperbolic basic set and the Liouville measure is its Bowen-Ruelle-Sinai measure. Then Theorems A and B imply:

**Corollary.** *The entropy of the geodesic flow of  $g \in A^r(M)$ ,  $r \leq 3$  with respect to the Liouville measure is a  $C^{r-3}$  function. The topological entropy of the geodesic flow of  $g \in A^r(M)$ ,  $r \leq 1$ , is a  $C^{r-1}$  function of  $g$ .*

For  $r=4$  the first part of this corollary was proved by Knieper and Weiss [11]. Theorems A and B can be extended and unified to entropies with respect to equilibrium states. Take  $X, A, U$  and  $\mathcal{U}$  as above. Denote  $C^\alpha(M, \mathbb{R})$ ,  $0 < \alpha < 1$ , the Banach space of  $\alpha$ -Hölder continuous real valued functions on  $M$ . Consider a function  $\psi: \mathcal{U} \rightarrow C^\alpha(M, \mathbb{R})$  and, for  $Y \in \mathcal{U}$ , denote  $\mu_Y$  the  $Y$ -invariant probability on the Borel  $\sigma$ -algebra of  $\mathcal{A}_Y$  that is the equilibrium state of  $\psi(Y)|_{\mathcal{A}_Y}$ . Let  $h_{\mu_Y}(Y|_{\mathcal{A}_Y})$  be its entropy and

$$P(Y) = P_Y(\psi(Y)) = h_{\mu_Y}(Y|_{\mathcal{A}_Y}) + \int \psi(Y) d\mu_Y$$

the pressure of  $(\psi(Y), \mathcal{A}_Y, Y)$ . The  $\Omega$ -stability theorem gives for each  $Y$  in  $\mathcal{U}$  a homeomorphism  $h_Y: A \rightarrow \mathcal{A}_Y$  such that it is Hölder continuous and sends orbits of  $(A, X)$  to orbits of  $(\mathcal{A}_Y, Y)$ . This topological equivalence  $h_Y$  is not unique because by composing with translations along orbits of  $\mathcal{A}_Y$  we get other topological equivalences. However this is the only obstruction to the uniqueness of  $h_Y$  and on Proposition 1.2 we choose one such  $h_Y$  such that the map  $\mathcal{U} \ni Y \mapsto h_Y \in C^\alpha(A, M)$  is  $C^{r-1}$ .

**Theorem C.** *If the map  $\mathcal{U} \ni Y \mapsto \psi(Y) \circ h_Y \in C^0(A, \mathbb{R})$  is  $C^s$  and  $\mathcal{U} \ni Y \mapsto \psi(Y) \circ h_Y \in C^\alpha(A, \mathbb{R})$  is  $C^{s-1}$ , then*

- (a)  $P: \mathcal{U} \rightarrow \mathbb{R}$  is  $C^s$ .
- (b)  $\mathcal{U} \ni Y \mapsto h_{\mu_Y}(Y|_{\mathcal{A}_Y})$  is  $C^{s-1}$ .
- (c) If  $0 < \alpha < 1$  is small enough and denoting  $(C^\alpha(M, \mathbb{R}))^*$  the dual Banach space of  $C^\alpha(M, \mathbb{R})$  then  $\mathcal{U} \ni Y \mapsto \mu_Y \in (C^\alpha(M, \mathbb{R}))^*$  is  $C^{s-1}$ .

In Sect. 1 we see that the map  $\mathcal{U} \ni Y \rightarrow h_Y \in C^\alpha(A, M)$  is  $C^r$  for some appropriate  $\alpha$ , so that Theorem C is valid when we consider for example a  $C^r$  map  $\psi: \mathcal{U} \rightarrow C^r(U, \mathbb{R})$  and a neighbourhood  $U$  of  $A$  in  $M$ . Considering  $\mu_Y$  as an element of the dual Banach space of  $(C^0(M, \mathbb{R}))^*$ , item (c) becomes false (see [15]).

Theorem A follows from item (a) of Theorem C and  $\psi \equiv 0$ . Theorem B follows from letting  $\psi(Y)(p) = -\frac{d}{dt} \log |\det(D_p \varphi_Y(p, t)|_{E^u(\varphi_Y(p, t))}|_{t=0}$ , where  $\varphi_Y(p, t)$  is the flow of  $Y$  and  $E^u(q)$  is the strong unstable subspace of  $Y$  at  $q \in A_Y$ . In Sect. 2 we prove that in this case the map  $\mathcal{U} \ni Y \rightarrow \psi(Y) \circ h_Y \in C^\alpha(A, \mathbb{R})$  is  $C^{r-2}$ . It also follows from Theorem C that the map  $\mathcal{U} \ni Y \rightarrow \int \psi(Y) d\mu_Y \in \mathbb{R}$  is  $C^{r-2}$ . Applying this for  $\psi(Y)$  of Theorem B, we see that the sum of the positive Lyapunov exponents is a  $C^{r-2}$  function of the vector field  $Y$  and that the rate of escape of a neighbourhood  $U$  of  $A_Y$ ,  $\lim_{T \rightarrow \infty} \frac{1}{T} \log \text{vol} \left( \bigcap_{t=0}^T \varphi_Y(U, -t) \right) = P_Y(\psi(Y))$  (see [5]) is a  $C^{r-1}$  function of the vector field  $Y \in \mathcal{X}^r(M)$ .

## 1 Preliminaries

Let  $M$  be a compact differentiable manifold and  $\phi_t: M \rightarrow M$  a differentiable flow. A closed,  $\phi_t$ -invariant set  $A$  without fixed points is *hyperbolic* if the tangent bundle restricted to  $A$  decomposes as the Whitney sum of three  $D\phi_t$ -invariant subbundles  $T_A M = E^0 \oplus E^s \oplus E^u$  where  $E^0$  is the 1-dimensional subbundle tangent to the flow and there are constants  $C, \lambda > 0$  satisfying:

- (i)  $|D\phi_t v| \leq C e^{-\lambda t} |v|$  for  $v \in E^s, t > 0$ .
- (ii)  $|D\phi_{-t} v| \leq C e^{-\lambda t} |v|$  for  $v \in E^u, t > 0$ .

A closed  $\phi_t$ -invariant subset  $A \subset M$  is a *basic set* for  $\phi_t$  if

- (a)  $A$  does not have fixed points and is hyperbolic.
- (b) The periodic orbits in  $A$  are dense in  $A$ .
- (c)  $\phi_t|_A$  is transitive (there is a dense orbit).
- (d) There is an open set  $U \supset A$  such that  $A = \bigcap_{t \in \mathbb{R}} \phi_t(U)$ .

From now on, fix an Axiom A basic set  $A \subset M$  of the vector field  $X \in \mathcal{X}^*(M)$  ( $*$  =  $r, r + \alpha, \infty$  or some  $\beta > 0$ ) and let  $\phi: M \times \mathbb{R} \rightarrow M$ ,  $\phi(p, t) = \phi_t(p)$  be its flow. We will always consider spaces of maps  $\mathcal{X}^*(M) \subset C^*(M, TM)$ ,  $C^*(A, M)$ ,  $C^*(A, TM)$ , etc. as Banach manifolds by composition with local charts. Let  $A, B$  be metric spaces. We say that a map  $f: A \rightarrow B$  is  $\alpha$ -Hölder continuous if

$$K(f) := |f|_\alpha := \sup_{d(x, y) < a} \frac{d(fx, fy)}{d(x, y)^\alpha} < \infty.$$

If  $B$  is a Banach space and  $K \subset A$  is compact, we write

$$|f|_0 := \sup_{x \in K} |f(x)|$$

and  $C^\alpha(K, B)$  for the Banach space of  $\alpha$ -Hölder maps, with the  $\alpha$ -Hölder norm  $\|f\| := |f|_0 + |f|_\alpha$ . Endow  $C^\alpha(A, B)$  with the topology given by the Hölder norm on compact parts of  $A$ .

Consider the space

$$C_\phi^\alpha(A, M) := \left\{ u \in X^\alpha(A, M) \mid D_\phi u(p) := \frac{d}{dt} u(\phi(p, t))|_{t=0} \text{ exists and is } \alpha\text{-Hölder} \right\},$$

with the topology of the  $\alpha$ -Hölder norm  $\|u\| + \|D_\phi u\|$ .

**1.1. Proposition** [structural stability] (a) *There exist  $0 < \beta < 1$  and a neighbourhood  $\mathcal{U} \subset \mathcal{X}^r(M)$  of  $X$  and  $C^{r-1}$  maps  $\mathcal{U} \rightarrow C_\phi^\beta(A, M)$ :  $Y \mapsto u_Y$  and  $\mathcal{U} \rightarrow C^\beta(A, [\frac{1}{2}, +\infty[)$ :  $Y \mapsto \gamma_Y$  such that  $Y \circ u_Y = \gamma_Y D_\phi u$ .*  
 (b) *Moreover, the maps  $\mathcal{U} \rightarrow C_\phi^0(A, M)$ :  $Y \mapsto \mathcal{U}_Y$  and  $\mathcal{U} \rightarrow C^0(A, [\frac{1}{2}, +\infty[)$ :  $Y \mapsto \gamma_Y$  are  $C^r$ .*

Case (a) has been proved in [9]. Case (b) has been proved in [8] for  $r=1$ . That proof can be immediately generalized to an arbitrary positive integer  $r$ .

Note that for  $Y$  near  $X$ , the topological equivalence  $u_Y$  is uniquely determined by  $u_Y(p) \in \exp(E_X^s(p) \oplus E_X^u(p))$ ,  $Y \circ u_Y = \gamma D_\phi u_Y$  and  $u_Y$  near the identity.

**1.2. Corollary.** *For  $Y \in \mathcal{U}$  consider the map  $\tau_Y: A \rightarrow \mathbb{R}^+$  defined by  $\psi(u_Y(\phi_{-1} p))$ ,  $\tau_Y(p) = u_Y(p)$ , where  $\psi$  is the flow of  $Y$ . Then*

$$\tau_Y(p) = \int_0^1 \gamma(\phi(p, s-1)) ds$$

and the map  $\mathcal{U} \rightarrow C^\beta(A, \mathbb{R}^+)$ :  $Y \mapsto \tau_Y$  is  $C^r$ .

## 2 Stability of the splitting

Let  $G$  be the Grassmann bundle of  $u$ -planes on  $TM$ ,  $u = \dim E_X^u$ , i.e. the set of pairs  $(p, E)$  with  $p \in M$  and  $E \subset T_p M$  a  $u$ -dimensional subspace.  $G$  has a natural structure of compact differentiable manifold where a parametrization around a subspace  $(p, E) \in G$  is  $U \times L(E, E^\perp) \rightarrow G$ ,  $(x, L) \mapsto D_x h$  (graph  $L$ ), where  $h: U \subset \mathbb{R}^n \rightarrow M$  is a parametrization of a neighbourhood of  $p$  and we identify  $E \approx (D_x h)^{-1} E$ . For  $Y \in \mathcal{X}^r(M)$  near  $X$ , consider the topological equivalence  $u_Y$  of Proposition 1.1 and its splitting  $TM|_{u_Y(A)} = E_Y^0 \oplus E_Y^s \oplus E_Y^u$ .

**2.1. Proposition.** *There exists a neighbourhood  $\mathcal{U}$  of  $X$  in  $\mathcal{X}^r(M)$  and  $\beta > 0$  such that the map  $\mathcal{U} \rightarrow C^\beta(A, G)$ :  $Y \mapsto (p \mapsto E_Y^u \circ u_Y(p))$  is  $C^{r-2}$  and the map  $\mathcal{U} \rightarrow C^0(A, G)$ :  $Y \mapsto E_Y^u \circ u_Y$  is  $C^{r-1}$ .*

*Proof.* Consider the product bundle  $\pi: TM \oplus G \rightarrow M$  of triples  $(p, v, E)$  with  $v \in T_p M$ ,  $E \subset T_p M$ . Then  $TM \oplus G$  is naturally a compact  $2n + u(n-u)$  manifold. For  $Y$  near  $X$  let  $\tau_Y \in C^\beta(A, \mathbb{R}^+)$  be as in (1.2). Let  $C_\phi^\beta(A, G)$  be the space of  $\beta$ -Hölder maps  $\sigma: A \rightarrow G$ ,  $\sigma(p) = (h(p), E(p))$  where  $D_\phi h(p) := \frac{d}{dt} \Big|_{t=0} h(\phi(p, t))$  is  $\beta$ -Hölder, with the topology of the  $\beta$ -Hölder norm on  $h$ ,  $D_\phi h$  and  $E$ . Consider

the map  $H: \mathcal{X}^r(M) \times C_\phi^\delta(A, \mathbb{R}^+) \times C_\phi^\beta(A, G) \rightarrow C^s(A, TM \oplus G)$ ,  $H(Y, \gamma, \sigma) = (Y \circ h - \gamma D_\phi h, D_1 \psi(h(\phi_{-1}p), \tau_Y(p))E(\phi_{-1}p))$  where  $D_1 \psi(q, s) = \frac{\partial \psi}{\partial q}(q, s)$ ,  $q \in M$ . Consider  $\sigma \in C_\phi^\beta(A, G)$  satisfying the equation  $H(Y, \gamma, \sigma) = (0, \sigma)$  and  $\sigma$  near  $\sigma_0(p) = (p, E_X^\sigma(p))$ . Then it is easy to see that  $h = u_Y$  and  $F(q) := E \circ u_Y^{-1}(q)$  is an invariant  $u$ -subbundle for  $Y$  on  $u_Y(A)$  near  $E_X^\sigma$ . So that  $q \mapsto F(q)$  should be the unstable subbundle for  $Y$ . We need to see the second component  $H_2$  of  $H$  in its local form in order to apply the implicit function theorem.

We can extend the splitting  $TM|_A = E_X^0 \oplus E_X^s \oplus E_X^u$  to a  $C^\gamma$ -splitting  $E^0 \oplus E^s \oplus E^u$  ( $\gamma$  as in (1.1)) of a neighbourhood  $U$  of  $A$ . In local coordinates, a subspace  $E \subset T_q M$ ,  $E \cap (E^0 \oplus E^s) = 0$  is seen as a linear map  $L: E^u(q) \rightarrow E^0(q) \oplus E^s(q)$ . The local expression for  $H_2$  is

$$(1) \quad H_2(Y, \sigma)(p) = [C(Y, \tau_Y p, h\phi_{-1}p) + D(Y, \tau_Y p, h\phi_{-1}p)L(\phi_{-1}p)] \\ \cdot [A(Y, \tau_Y p, h\phi_{-1}p) + B(Y, \tau_Y p, h\phi_{-1}p)L(\phi_{-1}p)]^{-1}$$

where

$$D_1 \psi_Y(q, \tau) = \frac{\partial \psi_Y}{\partial q}(q, \tau) = \begin{bmatrix} A(Y, \tau, q) & B(Y, \tau, q) \\ C(Y, \tau, q) & D(Y, \tau, q) \end{bmatrix}$$

in the splitting  $E^u \oplus (E^0 \oplus E^s)$ , for  $Y \in \mathcal{X}^r(M)$  near  $X$ ,  $\tau \in \mathbb{R}$  and  $q \in U$ . We can replace  $C_\phi^\beta(A, G)$  by  $C_\phi^\beta(A, \mathcal{L})$  where  $\mathcal{L}$  is the bundle of linear maps  $L(E^u, E^0 \oplus E^s)$ . Let  $F(Y, \gamma, \sigma) := H(Y, \gamma, \sigma) - (0, \sigma)$ . The formula (1) is analytic on  $L, C^{r-2}$  on  $h$  and  $C^{r-2}$  on  $Y$  by (1.2). So that for a suitable  $\beta < \gamma$ ,  $F$  is  $C^{r-2}$ . We need to check that  $D_{23}F(X, 1, E_X^u) = D_{23}H_1 \otimes (D_{23}H_2 - \text{Id})$  is invertible. From (1.1) we already know that  $D_{23}H_1$  is invertible. Since we have chosen maps on the bundle  $\mathcal{L} \rightarrow M$ , the inverse  $D_{23}F(X, 1, E_X^u)$  should have the form  $(D_{23}H_1)^{-1} \otimes (D_3H_2 - \text{Id})^{-1}$ . It is a standart fact (see [21]) that  $D_3H_2(X, 1, E_X^u)$  is a contraction onto  $C^0(A, \mathcal{L})$ . We leave to the reader the proof that, since in (1) only  $h$  and  $L$  are not Lipschitz, we can choose  $a > 0$  in the definition of Hölder norm such that  $D_3H_2(X, 1, E_X^u)$  is a contraction onto  $C^\beta(A, \mathcal{L})$ .  $\square$

### 3 Symbolic dynamics

For  $A = [A(i, j)] \in \{0, 1\}^{n \times n}$  an  $n \times n$  matrix of 0's and 1's we define

$$\Sigma = \Sigma_A := \{\bar{x} = (x_i)_{i=-\infty}^+ \in \{1, \dots, n\}^{\mathbb{Z}} \mid A(x_i, x_{i+1}) = 1 \quad \forall i \in \mathbb{Z}\} \\ \Sigma^+ = \Sigma_A^+ := \{\bar{x} = (x_i)_{i=0}^+ \in \{1, \dots, n\}^{\mathbb{Z}} \mid A(x_i, x_{i+1}) = 1 \quad \forall i \in \mathbb{N}\}$$

and  $\sigma: \Sigma \leftrightarrow$  by  $\sigma(\bar{x}) = (y_i)_{i=-\infty}^+$  where  $y_i = x_{i+1}$ . Similarly we define  $\sigma_+: \Sigma^+ \leftrightarrow$ . Endow  $\Sigma$  (resp.  $\Sigma^+$ ) with the metric  $d(\tilde{x}, \tilde{y}) = b^N$  where  $0 < b < 1$ ,  $N = \max\{m \mid x_k = y_k, \forall |k| < m\}$ . Then  $\Sigma$  (resp.  $\Sigma^+$ ) is compact and  $\sigma$  becomes a homeomorphism which is called a *subshift of finite type* if  $\sigma: \Sigma \leftrightarrow$  (resp.  $\sigma_+: \Sigma^+ \leftrightarrow$ ) is topologically transitive (i.e., for  $U, V$  non-empty open sets there is an  $n > 0$  with  $f^n U \cap V \neq \emptyset$ ). For  $\tau: \Sigma \rightarrow \mathbb{R}$  a positive continuous function consider the quotient space

$S(\Sigma, \tau) := \Sigma \times [0, +\infty[ \equiv$  where  $\left(x, \sum_{k=0}^n \tau(\sigma^k x)\right) \equiv (\sigma^{n+1} x, 0)$ , for any  $n \in \mathbb{N}$ . Then

$S(\Sigma, \tau)$  is a compact metric space and the flow  $f^t(x, s) = (x, s + t)$  on  $\Sigma \times \mathbb{R}$  induces a flow  $f^t$  on  $S(\Sigma, \tau)$  called the *suspension of  $\sigma$  at time  $\tau$* .

**3.1 Lemma** [3, 5] *There exists a topologically mixing subshift of finite type  $\sigma: \Sigma \rightarrow \Sigma$ , a positive  $\tau \in C^a(A, \mathbb{R}^+)$ , for some  $\alpha > 0$ , and a continuous surjection  $\pi: S(\Sigma, \tau) \rightarrow A$  such that*

$$\begin{array}{ccc} S(\Sigma, \tau) & \xrightarrow{f^t} & S(\Sigma, \tau) \\ \pi \downarrow & & \downarrow \pi \\ A & \xrightarrow{\phi_t} & A \end{array}$$

*commutes.*

#### 4 Entropy and equilibrium states

Let  $X$  be a compact metric space and  $f^t: X \rightarrow X$  be a flow ( $t \in \mathbb{R}$ ) or iterates of a homeomorphism  $g = f^1$  ( $t \in \mathbb{Z}$ ), and let  $\varphi: X \rightarrow \mathbb{R}$  be a continuous function. For given  $\varepsilon > 0$  and  $T > 0$  (resp.  $T \in \mathbb{N}$ ), a subset  $E \subset X$  is called  $(n, \varepsilon)$ -separated if

$$x, y \in E, x \neq y \Rightarrow d(f^t x, f^t y) > \varepsilon \quad \text{for some } t \in [0, T].$$

One defines the *topological pressure* of  $\varphi$ ,  $P(F, \varphi)$ ,  $F = (f^t)$  (resp.  $P(g, \varphi)$ ) by

$$P(F, \varphi) := \lim_{\varepsilon \rightarrow 0} \limsup_{T \rightarrow \infty} \frac{1}{T} \log(\sup \{ \sum_{x \in E} \exp S_T \varphi(x) \mid E \text{ is } (T, \varepsilon)\text{-separated} \})$$

where  $S_T \varphi(x) = \int_0^T \varphi(f^t x) dt$  (resp.  $S_T \varphi(x) = \sum_{n=0}^{T-1} \varphi(g^n x)$ ). The *topological entropy*

is defined to be the pressure of  $\varphi \equiv 0$ . Let  $\mathcal{M}(g)$  be the set of  $g$ -invariant Borel probability measures, for flows  $\mathcal{M}(F) = \bigcap_{t \in \mathbb{R}} \mathcal{M}(f^t)$ ,  $F = (f^t)$ . For a definition of

*metric entropy*  $h_\mu(g)$  and the variational principle

$$P(g, \varphi) = \sup_{\mu \in \mathcal{M}(g)} (h_\mu(g) + \int \varphi d\mu)$$

see [23]. An *equilibrium state* for  $\varphi$  with respect to  $g$  is a  $\mu \in \mathcal{M}(g)$  which realizes this supremum. If one lets  $\varphi^1(x) := \int_0^1 \varphi(f^t x) dt$ , then it is easy to see that

$P(F, \varphi) = P(f^1, \varphi^1)$  and that for  $\mu \in \mathcal{M}(F)$ ,  $\int \varphi^1 d\mu$ . Since  $\mathcal{M}(F) \subset \mathcal{M}(f^1)$  one has

$$h_\mu(f^1) + \int \varphi d\mu = h_\mu(f^1) + \int \varphi^1 d\mu \leq P(f^1, \varphi^1) = P(F, \varphi)$$

for  $\mu \in \mathcal{M}(F)$ . For  $\nu \in \mathcal{M}(f^1)$  let  $\mu$  be defined by  $\int \psi d\mu = \int \psi^1 d\nu$  for  $\psi$  measurable, then  $\mu \in \mathcal{M}(F)$  and ([6, p. 359–360]):

$$h_\mu(f^1) + \int \varphi^1 d\mu \geq h_\nu(f^1) + \int \varphi^1 d\nu.$$

It follows that

$$P(F, \varphi) = \sup_{\mu \in \mathcal{M}(F)} (h_\mu(f^1) + \int \varphi d\mu).$$

An equilibrium state for  $\varphi$  (with respect to  $F$ ) is a  $\mu \in \mathcal{M}(F)$  which realizes this supremum. For  $\nu \in \mathcal{M}(\sigma)$  and  $m$  the Lebesgue measure on  $\mathbb{R}$ ,  $\nu \times m$  gives measure 0 to the identifications  $(x, \tau(x)) \equiv (\sigma(x), 0)$  on  $Y = \{(x, t) \in \Sigma \times \mathbb{R} \mid 0 \leq t \leq \tau(x)\}$  so that  $\mu_\nu = (\nu \times m(Y))^{-1} \nu \times m|_Y$  induces a probability measure on  $S(\Sigma, \tau)$ . One can check that if  $\nu \in \mathcal{M}(\sigma)$  then  $\mu_\nu \in \mathcal{M}(F)$  for  $F = (f^1)$  the suspension flow and that  $\mathcal{M}(\sigma) \rightarrow \mathcal{M}(F)$ :  $\nu \rightarrow \mu_\nu$  is a bijection. It is known [4] that any  $\varphi \in C^\alpha(\Sigma, \mathbb{R})$  has a unique equilibrium state w.r.t.  $\sigma$  for any  $\alpha > 0$ .

**4.1 Lemma** [Bowen, Franco-Sanchez] *Let  $\varphi: S(\Sigma, \tau) \rightarrow \mathbb{R}$  be continuous,  $\phi(x) = \int_0^{\tau(x)} \varphi(x, t) dt$  and  $p = P(F, \varphi)$ . Assume that  $\phi \in C^\alpha(\Sigma, \mathbb{R})$  for some  $\alpha > 0$  then*

- (a) *There exists a unique equilibrium state  $\mu_\varphi \in \mathcal{M}(F)$  for  $\varphi$  w.r.t.  $F$ .*
- (b)  *$\mu_\varphi = \mu_{\nu_0}$  where  $\nu_0$  is the unique equilibrium state for  $\phi - p\tau$ .*
- (c)  *$P(\sigma, \phi - p\tau) = 0$ .*

*Proof.* Let  $\gamma = \phi - p\tau$ . Since  $\phi, \varphi \in C^\beta(\Sigma, \mathbb{R})$  for some  $\beta > 0$ , we have  $\gamma \in C^\beta(\Sigma, \mathbb{R})$  so that  $\gamma$  has a unique equilibrium state  $\nu_0$ . By Fubini's theorem, for any  $\nu \in \mathcal{M}(\tau)$ ,  $(\nu \times m)(Y) = \int \tau d\nu$  and  $\int \varphi d\mu_\nu = \frac{\int \phi d\nu}{\int \tau d\nu}$ . A theorem of Abramov [1] states that

$$h_{\mu_\nu}(f^1) = \frac{h_\nu(\tau)}{\int \tau d\nu}.$$

Hence

$$\begin{aligned} p = P(F, \varphi) &= \sup_{\mu \in \mathcal{M}(F)} (h_\mu(f^1) + \int \varphi d\mu) \\ &= \sup_{\nu \in \mathcal{M}(\tau)} \frac{(h_\nu(\tau) + \int \phi d\nu)}{\int \tau d\nu} \end{aligned}$$

because  $\nu \mapsto \mu_\nu$  is a bijection. Thus  $P(\sigma, \gamma) = \sup_{\nu} (h_\nu(\sigma) + \int (\phi - p\tau) d\nu) = 0$  with  $\nu$  attaining the supremum ( $\nu = \nu_0$ ) precisely if  $\mu_\nu$  is the unique equilibrium state for  $\varphi$ .  $\square$

By considering the conjugacy  $\pi$  of Lemma 3.1 we obtain equilibrium states for Axiom A basic sets  $\phi_i: A \leftrightarrow$ .

**4.2. Corollary** *For  $\phi_i: A \leftrightarrow$  a basic set and  $\varphi: A \rightarrow \mathbb{R}$  Hölder continuous,  $\varphi$  has a unique equilibrium state w.r.t.  $\phi_i$  and  $\mu_\varphi(A) = \pi^* \omega(A) = \omega(\pi^{-1}A)$  where  $\omega$  is the equilibrium state for  $\varphi \circ \pi$  on  $S(\Sigma, \tau)$  w.r.t.  $F = (f^1)$ .*



For  $\psi \in C^\alpha(\Sigma^+, \mathbb{R})$  we now introduce the Perron-Frobenius operator  $\mathcal{L}_\psi: C^0(\Sigma^+, \mathbb{R}) \hookrightarrow$

$$(\mathcal{L}_\psi \varphi)(x) := \sum_{\sigma_+(y)=x} \varphi(y) \exp(\psi(y)).$$

Say that  $\psi, \varphi \in C^0(\Sigma, \mathbb{R})$  (resp.  $C^0(\Sigma^+, \mathbb{R})$ ) are *homologous* if there exists  $u \in C^0(\Sigma, \mathbb{R})$  such that  $\psi = \varphi - u + u \circ \sigma$ . It this case  $\mu$  is an equilibrium state for  $\psi$  if and only if it is an equilibrium state for  $\varphi$ .

**4.3. Theorem** (Ruelle [20] see also [4]) *If  $\psi \in C^\alpha(\Sigma^+, \mathbb{R})$ ,  $0 < \alpha \leq 1$ , the spectrum of  $\mathcal{L}_\psi: C^\alpha(\Sigma^+, \mathbb{R}) \hookrightarrow$  consists in a simple isolated eigenvalue  $\lambda(\psi) > 0$  and a set contained in a disc  $\{z \in \mathbb{C} \mid |z| < \mu < \lambda(\psi)\}$ . The pressure is  $P(\sigma_+, \psi) = \log \lambda(\psi)$ . Moreover, there exists a strictly positive eigenfunction  $h_\psi \in C^\alpha(\Sigma^+, \mathbb{R})$  uniquely determined up to a scalar multiple and a unique Borel probability  $\nu_\psi$  on  $\Sigma^+$  satisfying*

- (a)  $\mathcal{L}_\psi h_\psi = \lambda_\psi h_\psi$
- (b)  $\int h_\psi d\nu_\psi = 1$
- (c)  $\mathcal{L}_\psi^* \nu_\psi = \lambda(\psi) \nu_\psi$
- (d)  $\mu_\psi := h_\psi \nu_\psi$  is  $\sigma_+$ -invariant and is the unique equilibrium state for  $\psi$  w.r.t.  $\sigma_+$ .
- (e)  $\mu_\psi = \mu_{\psi_1}$  if and only if  $\psi$  is homologous to  $\psi_1$ .
- (f) For all  $\varphi \in C^0(\Sigma^+, \mathbb{R})$ :  $\lim_{n \rightarrow +\infty} |\lambda(\psi)^{-n} \mathcal{L}_\psi^n \varphi - h_\psi \int \varphi d\nu_\psi|_0 = 0$ .

The following is just a reformulation of (f) for  $\varphi = 1$ .

**4.4. Corollary.** *If  $\psi \in C^\alpha(\Sigma^+, \mathbb{R})$ ,  $0 < \alpha \leq 1$ , then*

$$\lim_{n \rightarrow +\infty} \frac{1}{n} \log \sum_{\sigma_+^n(y)=x} \exp(S_n \psi)(y)$$

*uniformly on  $x \in \Sigma^+$ , where  $(S_n, \psi)(y) := \sum_{k=0}^{n-1} \psi(\sigma_+^k y)$ .*

**4.5. Corollary.** *If  $\psi \in C^0(\Sigma^+, \mathbb{R})$  the limit*

$$\lim_{n \rightarrow +\infty} \frac{1}{n} \log \sum_{\sigma_+^n(y)=x} \exp(S_n \psi)(y)$$

*exists for all  $x \in \Sigma^+$  and is independent of  $x$ .*

*Proof.* Define  $\Phi_n: C^0(\Sigma^+, \mathbb{R}) \hookrightarrow$  by  $\Phi_n(\psi)(x) = \frac{1}{n} \log \sum_{\sigma_+^n(y)=x} \exp(S_n \psi)(y)$ . Then

$$(\Phi'_n(\psi)\varphi)(x) = \sum_{\sigma_+^n(y)=x} \frac{\frac{1}{n}(S_n \varphi)(y) \exp(S_n \psi)(y)}{\sum_{\sigma_+^n(y)=x} \exp(S_n \psi)(y)}. \text{ Hence } |(\Phi'_n(\psi)\varphi)(x)| \leq |\varphi|_0 \text{ for all } x \in \Sigma^+. \text{ So that}$$

$$|\Phi'_n(\psi)|_0 \leq 1$$

for all  $n$ . Then the sequence of maps  $\Phi_n: C^0(\Sigma^+, \mathbb{R}) \hookrightarrow$  is uniformly Lipschitz and is pointwise convergent (by 4.4) in the dense subset  $C^\alpha(\Sigma^+, \mathbb{R}) \subset C^0(\Sigma, \mathbb{R})$ .

Therefore the sequence  $\Phi_n$  converges uniformly on compact subsets of  $C^0(\Sigma^+, \mathbb{R})$  to a continuous map  $\Phi: C^0(\Sigma^+, \mathbb{R}) \leftarrow$ . Since  $\Phi(\psi) \in C^0(\Sigma^+, \mathbb{R})$ ,  $0 < \alpha \leq 1$ , then, by the density of  $C^\alpha(\Sigma^+, \mathbb{R})$  in  $C^0(\Sigma^+, \mathbb{R})$  and the continuity of  $\Phi$  in  $C^0(\Sigma^+, \mathbb{R})$ , it follows that  $\Phi(\psi)$  is a constant function for each  $\psi \in C^0(\Sigma^+, \mathbb{R})$ .  $\square$

Using (4.5), for  $\psi \in C^0(\Sigma^+, \mathbb{R})$  define

$$P(\psi) = \lim_{n \rightarrow +\infty} \frac{1}{n} \log \sum_{\sigma_n^+ y = x} \exp(S_n \psi)(y).$$

**4.6. Corollary.** *For all  $0 < \alpha \leq 1$  the maps*

$$\begin{aligned} P: C^\alpha(\Sigma^+, \mathbb{R}) &\rightarrow \mathbb{R} \\ C^\alpha(\Sigma^+, \mathbb{R}) \ni \psi &\rightarrow v_\psi \in C^\alpha(\Sigma^+, \mathbb{R})^* \\ C^\alpha(\Sigma^+, \mathbb{R}) \ni \psi &\rightarrow h_\psi \in C^\alpha(\Sigma^+, \mathbb{R}) \\ C^\alpha(\Sigma^+, \mathbb{R}) \ni \psi &\rightarrow \mu_\psi = h_\psi v_\psi \in C^\alpha(\Sigma^+, \mathbb{R})^* \end{aligned}$$

*are real analytic.*

*Proof.* For a given  $\psi_0 \in C^\alpha(\Sigma^+, \mathbb{R})$  take disjoint circles  $\gamma_1$  and  $\gamma_2$  centered at  $\lambda(\psi_0)$  and 0 such that their interiors are disjoint and contain  $\text{Sp}(\mathcal{L}_{\psi_0})$ . Denote by  $S$  the space of continuous linear maps  $L: C^\alpha(\Sigma^+, \mathbb{C}) \leftarrow$  endowed with the norm topology. Let  $V$  be a neighbourhood of  $\mathcal{L}_{\psi_0}$  in  $S$  such that  $\text{Sp}(L) \subset \text{int}(\gamma_1) \cup \text{int}(\gamma_2)$  for all  $L \in V$ . Given  $L \in V$  define the spectral projection  $\pi_i(L): C^\alpha(\Sigma^+, \mathbb{C}) \leftarrow i = 1, 2$  by

$$\pi_i(L) := \frac{1}{2\pi i} \int_{\gamma_i} (L - zI)^{-1} dz$$

and let  $E_i(L) := \pi_i(L)(C^\alpha(\Sigma^+, \mathbb{C}))$ . It is well known that [7, 3.3]

$$C^\alpha(\Sigma^+, \mathbb{C}) = E_1(L) \oplus E_2(L)$$

$$I = \pi_1(L) + \pi_2(L)$$

$$\dim E_1(L) = 1$$

$\pi_i(L)$  is a projection and a complex analytic function of  $L$

$E_i(L)$  is  $L$ -invariant.

We can normalize  $h_{\psi_0}$  such that  $h_{\psi_0} = \pi_1(\mathcal{L}_{\psi_0}) \cdot 1$ . Take  $v^* \in C^\alpha(\Sigma^+, \mathbb{C})^*$  such that  $\langle v^*, h_{\psi_0} \rangle \neq 0$  and define for  $L \in V$

$$h(L) := \pi_1(L) \cdot 1, \quad \lambda(L) := \frac{\langle v^*, Lh(L) \rangle}{\langle v^*, h(L) \rangle}.$$

The map  $h: V \rightarrow C^\alpha(\Sigma^+, \mathbb{C})$  is analytic. The denominator of  $\lambda(L)$  is different from zero if  $V$  is taken small enough. Then the map  $\lambda: V \rightarrow \mathbb{C}$  is analytic. Define  $v: V \rightarrow C^\alpha(\Sigma^+, \mathbb{C})^*$  by

$$\langle v(L), \varphi \rangle = \frac{\pi_1(L)\varphi}{\pi_1(L)1}.$$

The function  $V \times C^\alpha(\Sigma^+, \mathbb{C}) \ni (L, \varphi) \mapsto \langle v(L), \varphi \rangle \in \mathbb{C}$  is analytic. Since  $E_1(L)$  is 1-dimensional and  $L$ -invariant  $Lh(L) = \lambda h(L)$  for some  $\lambda \in \mathbb{C}$ , using the definition of  $\lambda(L)$  we see that

$$Lh(L) = \lambda(L)h(L).$$

For  $L \in V$  consider the adjoint map  $L^*: C^\alpha(\Sigma^+, \mathbb{C}) \leftarrow$

$$\langle L^* v(L), \varphi \rangle = \langle v(L), L\varphi \rangle = \frac{\pi_1(L)L\varphi}{\pi_1(L)1} = \frac{L\pi_1(L)\varphi}{\pi_1(L)1} = \lambda(L) \frac{\pi_1(L)\varphi}{\pi_1(L)1} = \lambda(L) \langle v(L), \varphi \rangle$$

for any  $\varphi \in C^\alpha(\Sigma^+, \mathbb{C})$ . Hence

$$L^* v(L) = \lambda(L)v(L)$$

and  $h(\mathcal{L}_\psi) = h_\psi$ ,  $v(\mathcal{L}_\psi) = v_\psi$ ,  $\log \lambda(\psi) = P(\psi)$  are real analytic functions of  $\psi$  for  $\psi$  real.  $\square$

Now we return from  $\Sigma^+$  to  $\Sigma$ . Say that  $\psi \in C^\alpha(\Sigma^+, \mathbb{R})$  is “homologous” to  $\varphi \in C^\alpha(\Sigma, \mathbb{R})$  if  $\bar{\psi}$  is homologous to  $\varphi$ , where  $\bar{\psi}((x_i)_{i=-\infty}^{\infty}) = \psi((x_i)_{i=0}^{\infty})$ .

**4.7. Lemma.** *There exists a continuous linear map  $A: C^\alpha(\Sigma, \mathbb{R}) \rightarrow C^\beta(\Sigma^+, \mathbb{R})$ ,  $\beta = \alpha/2$ , such that  $A(\psi)$  is “homologous” to  $\psi$ . In particular  $A^*: C^\beta(\Sigma^+, \mathbb{R})^* \rightarrow C^\alpha(\Sigma, \mathbb{R})^*$ ,  $(A^* \mu)(\varphi) = \mu(A\varphi)$  is a continuous linear map.*

The proof appears in p. 11 of [4].

**4.8. Corollary.** *For any  $0 < \alpha \leq 1$  the maps*

*the pressure  $P: C^\alpha(\Sigma, \mathbb{R}) \rightarrow \mathbb{R}$*

$$C^\alpha(\Sigma, \mathbb{R}) \ni \psi \mapsto \mu_\psi \in C^\alpha(\Sigma, \mathbb{R})^*$$

*the entropy  $C^\alpha(\Sigma, \mathbb{R}) \ni \psi \mapsto h(\mu_\psi) = P(\psi) - \int \psi d\mu_\psi \in \mathbb{R}^+$*

*are analytic, where  $\mu_\psi$  is the equilibrium state of  $\psi$  w.r.t.  $\sigma$*

*Proof.* Use the commutative diagram

$$\begin{array}{ccc} C^\alpha(\Sigma, \mathbb{R}) & \xrightarrow{\text{equilibrium state}} & C^\alpha(\Sigma, \mathbb{R})^* \\ A \downarrow & & \downarrow A^* \\ C^\beta(\Sigma^+, \mathbb{R}) & \xrightarrow{\text{equilibrium state}} & C^\beta(\Sigma^+, \mathbb{R})^* \end{array}$$

for  $\beta = \alpha/2$ .  $\square$

Here we reproduce the arguments of [15] in order to gain one more degree of differentiability by considering  $P: C^0(\Sigma^+, \mathbb{R}) \rightarrow \mathbb{R}$ , except for the use of Manning’s curve [14] in order to realize  $\frac{dP}{d\psi}$ .

**4.9. Corollary.** *For all  $0 < \alpha \leq 1$ ,  $v_\psi$  is a weakly continuous function of  $\psi \in C^\alpha(\Sigma^+, \mathbb{R})$  i.e.*

$$\lim_{n \rightarrow +\infty} \int \varphi dv_{\psi_n} = \int \varphi dv_\psi$$

for every convergent sequence  $\psi_n \rightarrow \psi$  in  $C^\alpha(\Sigma^+, \mathbb{R})$  and all  $\varphi \in C^0(\Sigma^+, \mathbb{R})$ .

*Proof.* Let  $\psi_n \rightarrow \psi$  be a convergent sequence in  $C^\alpha(\Sigma^+, \mathbb{R})$  and suppose that  $v_{\psi_n}$  doesn't converge weakly to  $v_\psi$ . Then we can assume that  $v_{\psi_n}$  converges weakly to a probability  $v \neq v_{\psi_n}$ , and

$$\mathcal{L}_\psi^* v = \lim_{n \rightarrow +\infty} L_{\psi_n}^* v_{\psi_n} = \lim_{n \rightarrow +\infty} \lambda(\psi_n) v_{\psi_n} = \lambda(\psi) v.$$

Hence,  $v \in C^0(\Sigma^+, \mathbb{R})^* \subset C^\alpha(\Sigma^+, \mathbb{R})^*$  is an eigenvector of  $\mathcal{L}_\psi^*: C^\alpha(\Sigma^+, \mathbb{R})^* \leftrightarrow$  associated to the simple eigenvalue  $\lambda(\psi)$  of  $\mathcal{L}_\psi^*$ . So that  $v = \eta v_\psi$  for some  $\eta \in \mathbb{R}$ , but since  $v$  and  $v_\psi$  are probabilities  $v = v_\psi$ .  $\square$

**4.10. Corollary.** *If  $0 < \alpha \leq 1$  and  $\psi \in C^\alpha(\Sigma^+, \mathbb{R})$ , then the derivative  $P'(\psi): C^\alpha(\Sigma^+, \mathbb{R}) \rightarrow \mathbb{R}$  is given by*

$$P'(\psi)\varphi = \int \varphi d\mu_\psi.$$

*Proof.* For  $s \in \mathbb{R}$  consider the inequality given by the variational principle

$$f(s) := P(\psi + s\varphi) \geq h(\mu_\psi) + \int \psi d\mu_\psi + s \int \varphi d\mu_\psi =: g(s).$$

Then  $f(s)$  is an analytic curve which lies above the straight line  $g(s)$  and only touches it at  $s=0$ , hence  $P'(\psi)\varphi = f'(0) = g'(0) = \int \varphi d\mu_\psi$ .  $\square$

**4.11. Proposition** [Mañé] *Let  $N$  be a Banach manifold and let  $\Phi: N \rightarrow C^\alpha(\Sigma^+, \mathbb{R})$ ,  $0 < \alpha \leq 1$ , be a  $C^k$  map,  $k \geq 1$ , such that  $\Phi: N \rightarrow C^0(\Sigma^+, \mathbb{R})$  is  $C^{k+1}$ . Then  $P \circ \Phi: N \rightarrow \mathbb{R}$  is  $C^{k+1}$ .*

The proof of this requires two lemmas. For metric spaces  $K_1, K_2$  we say that a map  $f: K_1 \rightarrow K_2$  is *compact* if it maps bounded sets onto relatively compact sets. One can see that if a sequence of compact maps  $f_n: K_1 \rightarrow K_2$  converges to a map  $f: K_1 \rightarrow K_2$  uniformly on bounded sets, then  $f$  is compact.

**4.12. Lemma.** *Let  $E_1, E_2$  be Banach spaces and  $U \subset E_1$  an open set. If  $f: U \rightarrow E_2$  is a  $C^k$  compact map, then for all  $x \in U$ , the derivatives  $f^{(i)}(x): E_1 \times \dots \times E_1 \rightarrow E_2$  are compact for all  $1 \leq i \leq k$ .*

*Proof.* Given  $x \in U$  let  $B$  be the unit ball centered at 0 and define maps  $f_n: B \rightarrow E_2$  by

$$f_n(v) := n \left( f \left( x + \frac{1}{n} v \right) - f(x) \right).$$

Then the sequence  $f_n$  converges uniformly to  $f'(x)|_B$ . Since each map  $f_n$  is compact, it follows that  $f'(x)$  is compact. Now suppose that we have proved that  $f^{(i)}(x)$  is compact for  $1 \leq i < n$ . Define maps  $f_n: B \rightarrow E_2$  by

$$f_n(v) = n^m \left( f \left( x + \frac{1}{n} v \right) - f(x) - \sum_{i=1}^{m-1} \frac{1}{i!} f^{(i)}(x) \left( \frac{1}{n} v, \dots, \frac{1}{n} v \right) \right)$$

Then the sequence  $f_n$  converges uniformly to the map  $B \ni v \mapsto f^{(m)}(x)(v, \dots, v) \in E_2$ . Hence this map is compact. Since using the symmetry of the  $m$ -linear map  $f^{(m)}(x)$  it is possible to write  $f^{(m)}(x)(v_1, \dots, v_m)$  as a linear combination of the vectors  $f^{(m)}(x)(v_i, \dots, v_i)$ ,  $1 \leq i \leq m$ , it follows that  $f^{(m)}(x)$  is compact.  $\square$

**4.13. Lemma.** Let  $E_0, E_1, E_2$  be Banach spaces,  $U \subset E_0$  an open set and suppose that  $f: U \rightarrow E_1, L: E_1 \rightarrow E_2$  and  $P: E_2 \rightarrow \mathbb{R}$  are maps satisfying

- (a)  $L$  is linear and compact.
- (b)  $f$  is  $C^k, k \geq 0$
- (c)  $L \circ f$  is  $C^{k+1}$
- (d)  $P \circ L$  is  $C^{k+1}$
- (e) There exists a function  $T$  that to each  $x \in E_1$  associates a continuous linear map  $T(x): E_2 \rightarrow \mathbb{R}$  satisfying

$$(1) \quad (P \circ L)'(x) = T(x)L$$

for all  $x \in E_1$ , and

$$(2) \quad \lim_{n \rightarrow +\infty} T(x_n)v = T(\lim x_n)v$$

for every convergent sequence  $\{x_n\} \subset E_1$  and all  $v \in E$ .  
Then  $P \circ L \circ f$  is  $C^{k+1}$ .

*Proof.* Clearly  $P \circ L \circ f$  is  $C^k$  because  $P \circ L$  is  $C^k$  and  $f$  is  $C^k$ . Suppose that  $k \geq 1$ . The derivative  $(P \circ L \circ f)^{(k)}(x)$  can be written as the sum of

$$(3) \quad (P \circ L)'(f(x)) \cdot f^{(k)}(x)$$

and a linear combination of compositions of derivatives  $(P \circ L)^{(i)}$  and  $f^{(j)}$  with  $1 < i \leq k$  and  $1 \leq j < k$ . Hence all these terms are  $C^1$ , because  $f$  is  $C^k$  and  $P \circ L$  is  $C^{k+1}$ . This means that in order to prove that  $f$  is  $C^{k+1}$  we have only to prove that (3) is  $C^1$ . Observe that

$$\begin{aligned} & (P \circ L)'(f(x+tw)) \cdot f^{(k)}(x+tw) - (P \circ L)'(f(x)) f^{(k)}(x) \\ &= ((P \circ L)'(f(x+tw)) - (P \circ L)'(f(x))) f^{(k)}(x+tw) \\ & \quad + (P \circ L)'(f(x)) (f^{(k)}(x+tw) - f^{(k)}(x)). \end{aligned}$$

Since  $P \circ L$  is  $C^2$  by (d) and the assumption  $k \geq 1$ , it follows that

$$\lim_{t \rightarrow 0} \frac{1}{t} ((P \circ L)'(f(x+tw)) - (P \circ L)'(f(x))) f^{(k)}(x+tw) = ((P \circ L)''(f(x))(f'(x) \cdot w)) f^{(k)}(x).$$

Moreover, by (1):

$$(P \circ L)'(f(x))(f^{(k)}(x+tw) - f^{(k)}(x)) = T(fx)((Lf)^{(k)}(x+tw) - (Lf)^{(k)}(x)).$$

Hence, since  $Lf$  is  $C^{k+1}$ ,

$$\lim_{t \rightarrow 0} \frac{1}{t} T(fx) \cdot ((Lf)^{(k)}(x+tw) - (Lf)^{(k)}(x)) = T(fx) \cdot ((Lf)^{(k+1)}(x) \cdot w).$$

Thus

$$\begin{aligned} & \lim_{t \rightarrow 0} \frac{1}{t} ((P \circ L)'(f(x+tw)) f^{(k)}(x+tw) - (P \circ L)'(f(x)) f^{(k)}(x)) \\ &= (P \circ L)''(f(x))(f'(x) \cdot w) f^{(k)}(x) + T(fx)(Lf)^{(k+1)}(x) \cdot w. \end{aligned}$$

Therefore, if we prove that this  $(k+1)$ -linear map is a continuous function of  $x$ , it will follow that (2) is  $C^1$  and then that  $P \circ L \circ f$  is  $C^{k+1}$ . Since  $P \circ L$  is  $C^2$  and  $f$  is  $C^k$  it follows that the first term of the sum depends continuously on  $x$ . To prove the continuity of  $T(fx)(Lf)^{(k+1)}(x)$  first observe that if  $x_n \rightarrow x$  and  $S \subset E_2$  is a relatively compact set then, by (2),  $T(x_n)|_S$  converges uniformly to  $T(x)|_S$ . Moreover,  $Lf$  is compact because  $L$  is compact and then, by the previous lemma,  $(Lf)^{(k+1)}(y)$  is compact for all  $y \in E_0$ . Let  $B$  be the unit ball of  $E_0 \times \frac{k+1}{\dots} \times E_0$ . Define

$$S = (Lf)^{(k+1)}(x)B \cup \left( \bigcup_{n \geq 1} (Lf)^{(k+1)}(x_n)B \right).$$

This set is relatively compact because every sequence  $\{u_n\} \subset S$  either has a subsequence contained in some  $(Lf)^{(k)}(p)B$ ,  $p \in \{x, x_1, \dots\}$  (and then, since this set is relatively compact, has a convergent subsequence) or has a subsequence that can be written as

$$u_{n_j} = (Lf)^{(k+1)}(x_{m_j}) \ominus_{m_j}$$

with  $\ominus_{m_j} \in B$  and  $m_j \rightarrow +\infty$  when  $j \rightarrow +\infty$ . But now, by the compacity of  $(Lf)^{(k+1)}(x)$ , we can assume that the sequence  $(Lf)^{(k+1)}(x) \ominus_{m_j}$ ,  $j \geq 1$ , converges to a point  $y \in E_2$  and then it is easy to prove that  $(Lf)^{(k+1)}(x_{m_j}) \ominus_{m_j}$  converges to  $y$ . This concludes the proof of the relative compacity of  $S$  and then  $T(x)|_S$  converges uniformly to  $T(x)|_S$ . Since  $(Lf)^{(k+1)}(x)B \subset S$  and  $(Lf)^{(k+1)}(x_n)B \subset S$  for all  $n \geq 1$ , it follows that  $T(x_n)(Lf)^{(k+1)}(x_n)|_B$  converges to  $T(x)(Lf)^{(k+1)}(x)|_B$  uniformly. This completes the proof of the lemma when  $k \geq 1$ . The case  $k=0$  is handled by similar methods.  $\square$

*Proof of (4.11)* We apply Lemma 4.13 to an open set  $U \subset N$ , the Banach spaces  $E_1 = C^\alpha(\Sigma^+, \mathbb{R})$  and  $E_2 = C^0(\Sigma^+, \mathbb{R})$ , the  $C^k$  map  $\Phi: U \rightarrow C^\alpha(\Sigma^+, \mathbb{R})$ , the compact linear map  $i: C^\alpha(\Sigma^+, \mathbb{R}) \rightarrow C^0(\Sigma^+, \mathbb{R})$  given by the inclusion and the function  $P: C^0(\Sigma^+, \mathbb{R}) \rightarrow \mathbb{R}$ . Hypothesis (a), (b) and (c) are obviously satisfied. Hypothesis (d) is satisfied because we proved (4.6) that  $P: C^\alpha(\Sigma^+, \mathbb{R}) \rightarrow \mathbb{R}$  is real analytic. To check (2) associate, to each  $\psi \in C^\alpha(\Sigma^+, \mathbb{R})$ , the functional  $T(\psi) \in C^0(\Sigma^+, \mathbb{R})^*$  given by  $T(\psi)\varphi = \int \varphi d\mu_\psi = \int \varphi h_\psi d\nu_\psi$ . Then, by (4.10),  $(P \circ i)'(\psi)\varphi = T(\psi)\varphi$ , thus proving property (1) of hypothesis (e). Property (2) follows from the fact that  $\nu_\psi$  is, by (4.9), a weakly continuous function of  $\psi \in C^\alpha(\Sigma^+, \mathbb{R})$  and  $h_\psi$  is a continuous (in fact real analytic) function of  $\psi$  by (4.6). Then (4.13) can be applied and proves that  $P \circ i \circ \phi = P \circ \phi$  is  $C^{k+1}$ .  $\square$

## 5 Proofs of the theorems

**5.1. Lemma.** *There exists  $\alpha > 0$ , a subshift of finite type  $\Sigma$ , a neighbourhood  $\mathcal{U} \subset \mathcal{X}^r(M)$  of  $X$  and  $C^{r-1}$  maps  $\tau: \mathcal{U} \rightarrow C^\alpha(\Sigma, \mathbb{R})$ ,  $k: \mathcal{U} \rightarrow C^\alpha(\Sigma, M)$  such that  $\tau: \mathcal{U} \rightarrow C^0(\Sigma, \mathbb{R})$ ,  $k: \mathcal{U} \rightarrow C^0(\Sigma, M)$  are  $C^r$  and for  $Y \in \mathcal{U}$*

$$\begin{array}{ccc} S(\Sigma, \tau_Y) & \xrightarrow{f^t} & S(\Sigma, \tau_Y) \\ \kappa_Y \downarrow & & \downarrow \kappa_Y \\ A(Y) & \xrightarrow{\psi_Y} & A(Y) \end{array}$$

conmmutes. Where  $\psi_Y$  is the flow of  $Y$ ,  $\overline{k_Y}(x, t) = \psi_Y(k_Y(x), t)$  for  $x \in \Sigma$ ,  $0 \leq t < \tau_Y(x)$  and  $A(Y) = \bigcap_{t \in \mathbb{R}} \psi_Y(U, t)$  is the corresponding basic set for  $Y \in \mathcal{U}$  where  $U$  is a small neighbourhood of  $A$ .

*Proof.* Take  $\Sigma$ ,  $\pi$ ,  $\tau$  as in Lemma 3.1 and  $u_Y$ ,  $\gamma_Y$  as in Proposition 1.1. Let  $k_Y(x) := u_Y \circ \pi(x)$  and

$$\tau_Y(x) := \int_0^{\tau(\pi x)} \gamma_Y(\phi(\pi x, s))^{-1} ds$$

where  $\phi(x, t)$  is the flow of  $X$ . Then  $\tau_Y$  is the solution of  $\psi_Y(u_Y(\pi x), \tau_Y(\pi x)) = u_Y(\phi(\pi x, \tau_Y(\pi x)))$ ,  $x \in \Sigma$ , with  $\tau_X = \tau$ . From this the lemma follows easily.  $\square$

5.2. *Proof of theorems.* Let  $\mathcal{U}$  be as in Lemma 5.1. For  $Y \in \mathcal{U}$ , let  $\varphi_Y \in C^2(\Sigma, \mathbb{R})$  be  $\varphi_Y(x) := \int_0^{\tau_Y(x)} \psi(Y) \circ \overline{k_Y}(x, s) ds$ . Then the map  $\mathcal{U} \ni Y \mapsto \varphi_Y \in C^0(\Sigma, \mathbb{R})$  is  $C^s$ . The pressure  $P_Y(\psi(Y)) =: p_Y$  is given by  $P(\varphi_Y - p_Y \tau_Y) = 0$  where  $P$  is the pressure on  $(\Sigma, \sigma)$ . By Proposition 4.11, the function  $G: \mathcal{U} \times \mathbb{R} \rightarrow \mathbb{R}$ ,  $G(Y, s) := P(\varphi_Y - p_Y \tau_Y)$  is  $C^s$ . By the same argument as in Corollary 4.10 we have  $\frac{\partial G}{\partial s}(X, p_X) = - \int_X \tau_X d\nu_X < 0$ , where  $\nu_Y$  is the equilibrium state of  $-p_Y \tau_Y$  on  $(\Sigma, \sigma)$  for  $Y \in \mathcal{U}$ .

So that the invertibility condition holds and the implicit function can be applied.

By Lemma 4.1(b) the equilibrium state  $\mu_Y$  for  $\psi(Y)$  on  $(A(Y), Y)$  is given by

$$\mu_Y(\varphi) = \frac{\nu_Y(\varphi)}{\int \tau_Y d\nu_Y}, \quad \text{for } \varphi \in C^0(M, \mathbb{R})$$

where  $\phi(x) = \int_0^{\tau_Y(x)} \varphi(\overline{k_Y}(x, s)) ds$ ,  $x \in \Sigma$ . Thus by Corollary 4.8,

$Y \mapsto \mu_Y \in (C^2(M, \mathbb{R}))^*$  is  $C^{s-1}$ . The differentiability of the metric entropy can be seen using the variational principle  $h_\mu = P(\psi) - \int \psi d\mu$ . This completes the proof of Theorem C.

In order to prove Theorem B, take  $\mathcal{U}$  as in (2.1). For  $Y \in \mathcal{U}$  consider the function  $\varphi_Y^\mu: \Sigma \rightarrow \mathbb{R}$ ,

$$\varphi_Y^\mu(x) := -\log |\det D_1 \phi_Y(u_Y \circ k_Y(x), \tau_Y(x))|_{E_Y^\mu \circ u_Y \circ k_Y(x)}|$$

where  $\tau_Y: \Sigma \rightarrow \mathbb{R}$  is as in (5.1) and  $\phi_Y$  is the flow of  $Y$ . Then by (2.1) and (4.1), the map  $Y \mapsto \varphi_Y^\mu \in C^\alpha(\Sigma, \mathbb{R})$  is  $C^{r-2}$  for a suitable  $\alpha > 0$  and  $Y \mapsto \varphi_Y^\mu \in C^\alpha(\Sigma, \mathbb{R})$  is  $C^{r-1}$ . An obvious adaptation of the arguments above conclude the proof of Theorem B.  $\square$

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