

PROCESAMIENTO DE IMÁGENES USANDO CUDA

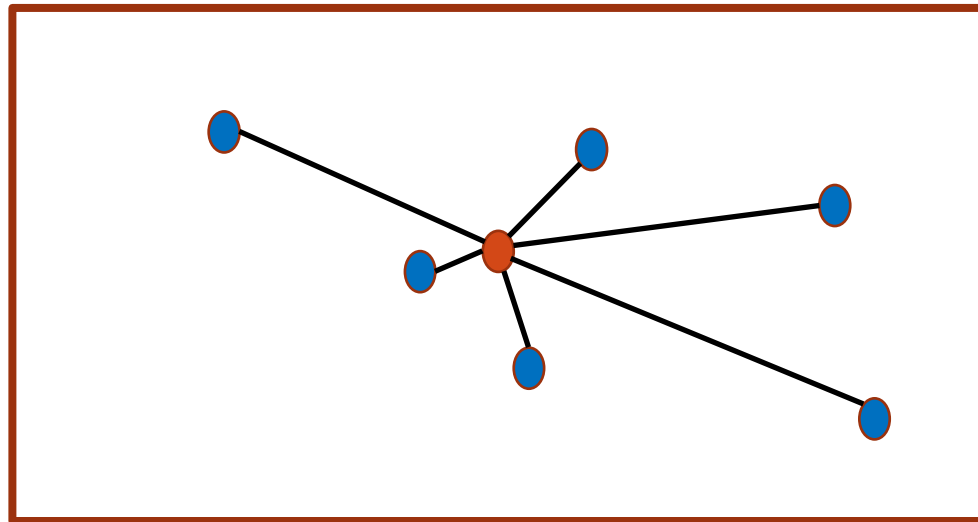
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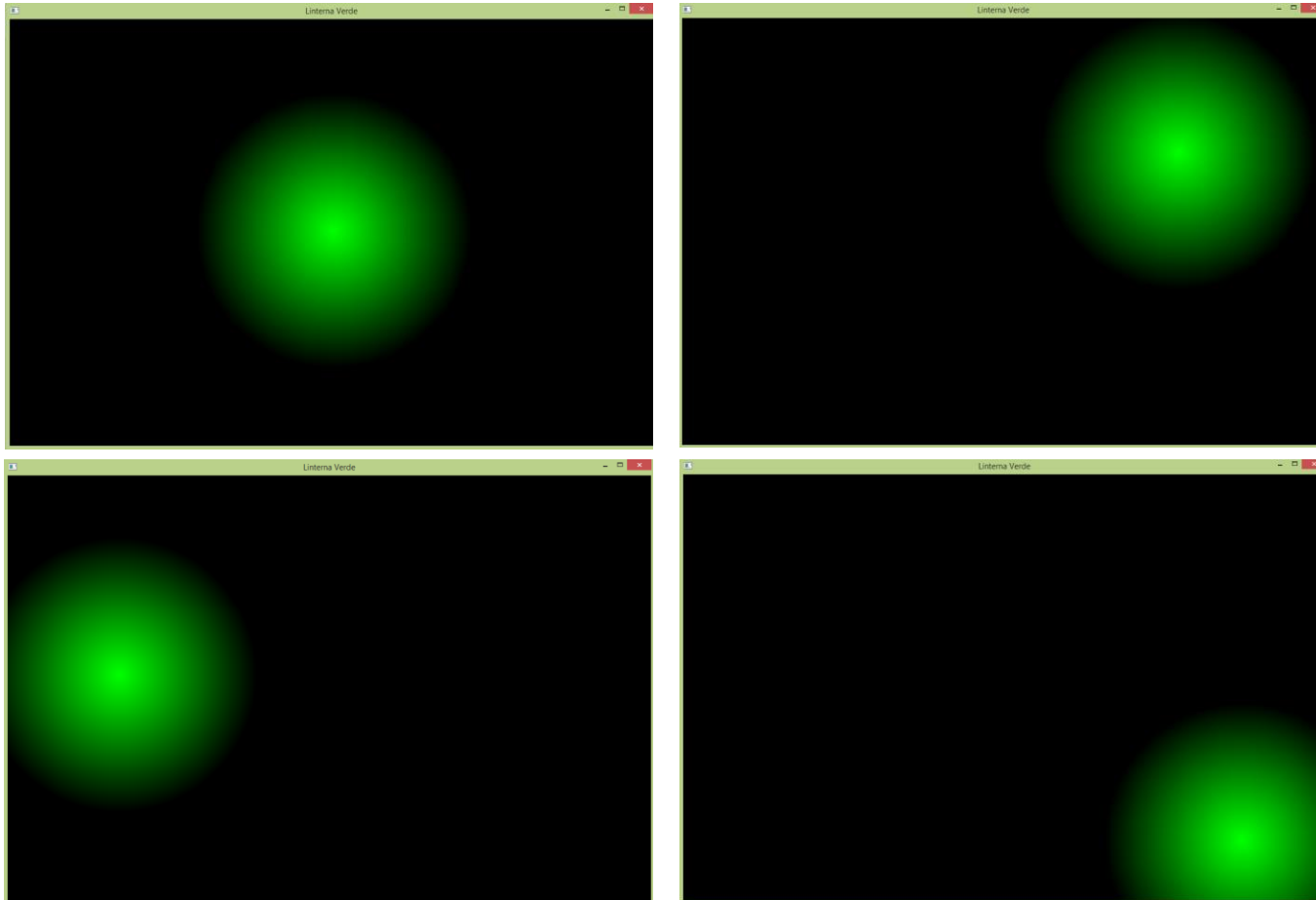
DIST_2D

- Calcula la distancia desde un punto de referencia en el plano a cada miembro de una malla uniforme de puntos 2D



Storti, D., & Yurtoglu, M. (2015). *CUDA for engineers: an introduction to high-performance parallel computing*. Addison-Wesley Professional.

APLICACIÓN: LINTERNA VERDE



LINTERNA VERDE (MAIN.CPP)

```
interactions.h  kernel.h  kernel.cu  LinternaVerde_main.cpp*  -  X
LinternaVerde  (Global Scope)
1  /*
2  Ejemplo tomado de:
3  Storti, D., & Yurtoglu, M. (2015).
4  CUDA for engineers: an introduction to high-performance parallel computing.
5  Addison-Wesley Professional.
6  Chapter 2.
7  Tomando este ejemplo, vamos a crear una "Linterna Verde" que se mueva a
8  una posición indicada por el cursor.
9
10 * Vamos a agregar al proyecto la carpeta del inc y lib para lo del OpenGL del SDK de CUDA
11 C:\ProgramData\NVIDIA Corporation\CUDA Samples\v10.1\common\inc
12 C:\ProgramData\NVIDIA Corporation\CUDA Samples\v10.1\common\lib\x64
13 */
14
15
16 #include "kernel.h"
17 #include <stdio.h>
18 #include <stdlib.h>
19 #ifdef _WIN32
20 #define WINDOWS_LEAN_AND_MEAN
21 #define NOMINMAX
22 #include <windows.h>
23 #endif
24 #ifdef __APPLE__
25 #include <GLUT/glut.h>
26 #else
27 #include <GL/glew.h>
28 #include <GL/freeglut.h>
```

```

29     #endif
30 #include <cuda_runtime.h>
31 #include <cuda_gl_interop.h>
32 #include "interactions.h"
33 #include <math.h>
34 #include <time.h>
35
36 // texture and pixel objects
37 GLuint pbo = 0; // OpenGL pixel buffer object
38 GLuint tex = 0; // OpenGL texture object
39 struct cudaGraphicsResource *cuda_pbo_resource;
40
41 #define Parallel_GPU
42
43 //Serial CPU
44 unsigned char clip_CPU(int n) { return n > 255 ? 255 : (n < 0 ? 0 : n); }
45 void kernelLauncher_Serial_CPU(uchar4 *h_out, int w, int h, int2 pos) {
46     for (int r = 0; r < h; r++) {
47         for (int c = 0; c < w; c++) {
48             const int i = c + r*w; // 1D indexing
49             const int dist = sqrtf((c - pos.x)*(c - pos.x) + (r - pos.y)*(r - pos.y));
50             const unsigned char intensity = clip_CPU(255 - dist);
51             h_out[i].x = 0;
52             h_out[i].y = intensity;
53             h_out[i].z = 0;
54             h_out[i].w = 255;
55         }
56     }
57 }

```

```

59 void render() {
60
61     uchar4 *d_out = 0;
62     cudaGraphicsMapResources(1, &cuda_pbo_resource, 0);
63     cudaGraphicsResourceGetMappedPointer((void **)&d_out, NULL, cuda_pbo_resource);
64 #ifdef Parallel_GPU
65     kernelLauncher(d_out, W, H, loc);
66 #else
67     uchar4 *h_out;
68     h_out = (uchar4 *)malloc(W*H * sizeof(uchar4));
69
70     kernelLauncher_Serial_CPU(h_out, W, H, loc);
71
72     cudaMemcpy(d_out, h_out, W*H * sizeof(uchar4), cudaMemcpyHostToDevice);
73     free(h_out);
74 #endif // Parallel_GPU
75     cudaGraphicsUnmapResources(1, &cuda_pbo_resource, 0);
76 }
77
78 void drawTexture() {
79     glTexImage2D(GL_TEXTURE_2D, 0, GL_RGBA, W, H, 0, GL_RGBA, GL_UNSIGNED_BYTE, NULL);
80     glEnable(GL_TEXTURE_2D);
81     glBegin(GL_QUADS);
82     glTexCoord2f(0.0f, 0.0f); glVertex2f(0, 0);
83     glTexCoord2f(0.0f, 1.0f); glVertex2f(0, H);
84     glTexCoord2f(1.0f, 1.0f); glVertex2f(W, H);
85     glTexCoord2f(1.0f, 0.0f); glVertex2f(W, 0);
86     glEnd();
87     glDisable(GL_TEXTURE_2D);
88 }

```

```

89 void display() {
90     render();
91     drawTexture();
92     glutSwapBuffers();
93 }
94
95 void initGLUT(int *argc, char **argv) {
96     glutInit(argc, argv);
97     glutInitDisplayMode(GLUT_RGBA | GLUT_DOUBLE);
98     glutInitWindowSize(W, H);
99     glutCreateWindow(TITLE_STRING);
100     #ifndef __APPLE__
101         glewInit();
102     #endif
103 }
104
105 void initPixelBuffer() {
106     glGenBuffers(1, &pbo);
107     glBindBuffer(GL_PIXEL_UNPACK_BUFFER, pbo);
108     glBufferData(GL_PIXEL_UNPACK_BUFFER, 4 * W*H * sizeof(GLubyte), 0, GL_STREAM_DRAW);
109     glGenTextures(1, &tex);
110     glBindTexture(GL_TEXTURE_2D, tex);
111     glTexParameteri(GL_TEXTURE_2D, GL_TEXTURE_MIN_FILTER, GL_NEAREST);
112     cudaGraphicsGLRegisterBuffer(&cuda_pbo_resource, pbo, cudaGraphicsMapFlagsWriteDiscard);
113 }
114
115 void exitfunc() {
116     if (pbo) {
117         cudaGraphicsUnregisterResource(cuda_pbo_resource);
118         glDeleteBuffers(1, &pbo);
119         glDeleteTextures(1, &tex);
120     }
121 }

```

```

123 int main(int argc, char** argv) {
124     printInstructions();
125     initGLUT(&argc, argv);
126     gluOrtho2D(0, W, H, 0);
127     glutKeyboardFunc(keyboard);
128     glutSpecialFunc(handleSpecialKeypress);
129     glutPassiveMotionFunc(mouseMove);
130     glutMotionFunc(mouseDrag);
131     glutDisplayFunc(display);
132     initPixelBuffer();
133     glutMainLoop();
134     atexit(exitfunc);
135     return 0;
136 }

```

LINTERNA VERDE (INTERACTIONS.H)

```
1  #ifndef INTERACTIONS_H
2  #define INTERACTIONS_H
3  #define W 1200
4  #define H 800
5  #define DELTA 5 // pixel increment for arrow keys
6  #define TITLE_STRING "Linterna Verde"
7  int2 loc = { W / 2, H / 2 };
8  bool dragMode = false; // mouse tracking mode
9
10 void keyboard(unsigned char key, int x, int y) {
11     if (key == 'a') dragMode = !dragMode; // toggle tracking mode
12     if (key == 27) exit(0);
13     glutPostRedisplay();
14 }
15
16 void mouseMove(int x, int y) {
17     if (dragMode) return;
18     loc.x = x;
19     loc.y = y;
20     glutPostRedisplay();
21 }
22
23 void mouseDrag(int x, int y) {
24     if (!dragMode) return;
25     loc.x = x;
26     loc.y = y;
27     glutPostRedisplay();
28 }
```

```
30 void handleSpecialKeyPress(int key, int x, int y) {
31     if (key == GLUT_KEY_LEFT) loc.x -= DELTA;
32     if (key == GLUT_KEY_RIGHT) loc.x += DELTA;
33     if (key == GLUT_KEY_UP) loc.y -= DELTA;
34     if (key == GLUT_KEY_DOWN) loc.y += DELTA;
35     glutPostRedisplay();
36 }
37
38 void printInstructions() {
39     printf("flashlight interactions\n");
40     printf("a: toggle mouse tracking mode\n");
41     printf("arrow keys: move ref location\n");
42     printf("esc: close graphics window\n");
43 }
44
45 #endif
```


LINTERNA VERDE (KERNEL.H)

```
1  #ifndef KERNEL_H
2  #define KERNEL_H
3
4  struct uchar4;
5  struct int2;
6
7  void kernelLauncher(uchar4 *d_out, int w, int h, int2 pos);
8
9  #endif
```

LINTERNA VERDE (KERNEL.CU)

```
1  #include "kernel.h"
2  #define TX 32
3  #define TY 32
4
5  device
6  unsigned char clip(int n) { return n > 255 ? 255 : (n < 0 ? 0 : n); }
7
8  __global__
9  void distanceKernel(uchar4 *d_out, int w, int h, int2 pos) {
10     const int c = blockIdx.x*blockDim.x + threadIdx.x;
11     const int r = blockIdx.y*blockDim.y + threadIdx.y;
12     if ((c >= w) || (r >= h)) return; // Check if within image bounds
13     const int i = c + r*w; // 1D indexing
14     const int dist = sqrtf((c - pos.x)*(c - pos.x) + (r - pos.y)*(r - pos.y));
15     const unsigned char intensity = clip(255 - dist);
16     d_out[i].x = 0;
17     d_out[i].y = intensity;
18     d_out[i].z = 0;
19     d_out[i].w = 255;
20 }
21
22 void kernellauncher(uchar4 *d_out, int w, int h, int2 pos) {
23     const dim3 blockSize(TX, TY);
24     const dim3 gridSize = dim3((w + TX - 1) / TX, (h + TY - 1) / TY);
25     distanceKernel << <gridSize, blockSize >> >(d_out, w, h, pos);
26 }
```

LEER IMAGEN USANDO OPENCV

```
13  #include <opencv2/opencv.hpp>
14
15  int main(void){
16      cv::Mat Image;
17
18      //desde el disco duro
19      Image = cv::imread("../images/flowers8.png");
20
21      int nCols=Image.cols;
22      int nFils=Image.rows;
23
24      printf("\nLeyendo imagen de %d x %d pixeles...\n", nFils, nCols);
25
26      return(0);
27  }
```

Para compilar:

```
g++ `pkg-config --cflags opencv` LeerImagen.cpp -o LeerImagen `pkg-config --libs opencv`
```

```
g++ `pkg-config --cflags opencv4` LeerImagen.cpp -o LeerImagen `pkg-config --libs opencv4`
```

MODIFICAR IMAGEN A COLOR

```
4  /*CUDA*/
5  #include "cuda_runtime.h"
6
7  /*OpenCV*/
8  #include <opencv2/highgui/highgui.hpp>
9
10 #include "ModificarImagen.h"
11
12 int main(int argc, char **argv){
13     cudaSetDevice(0);
14     /*Host Variables*/
15     int imageW, imageH;      //Tamaño de la imagen
16     cv::Mat frame_Original;  //Imagen original
17     cv::Mat frame_Modified; //Imagen modificada
18     /*Device Variables*/
19     uchar3 *Image_dev;
20
21     //cv::namedWindow("Original Frame",CV_WINDOW_AUTOSIZE);
22     //cv::namedWindow("Modified Frame",CV_WINDOW_AUTOSIZE);
23
24     /*Load Image*/
25     frame_Original = cv::imread("../images/Estacion_MR.jpg",1);
26
27     //cv::imshow("Original Frame", frame_Original);
```



MODIFICAR IMAGEN A COLOR (C1)

```
29     /*Size of Image*/
30     imageW=frame_Original.cols;
31     imageH=frame_Original.rows;
32     size_t size=3*imageW*imageH;
33
34     //Create Host memory
35     frame_Modified.create(imageH, imageW,CV_8UC(3));
36
37     /*Create device memory*/
38     cudaMalloc((void **)&Image_dev,size);
39
40     /*Copy Memory (Host-->Device)*/
41     cudaMemcpy(Image_dev,frame_Original.data,size,cudaMemcpyHostToDevice);
42
43     /*Define the size of the grid and thread blocks*/
44     dim3 threads(512,1,1);
45     int N=imageW * imageH;
46     dim3 grid(N/threads.x + (N%threads.x == 0 ? 0:1),1,1);
47     /*Launch the Kernel Function*/
48     CUDA_Modificar_Imagen(Image_dev,N,grid,threads);
```

MODIFICAR IMAGEN A COLOR (C2)

```
50     /*Copy Memory (Device-->Host)*/
51     cudaMemcpy(frame_Modified.data,Image_dev,size,cudaMemcpyDeviceToHost);

53     //cv::imshow("Modified Frame", frame_Modified);
54     //cv::waitKey(0);
55     //Guardar el resultado
56     cv::imwrite("../images/Estacion_MR_Modificada.jpg", frame_Modified);

58     /*Clean Memory*/
59     /*Host*/
60     //cv::destroyWindow("Original Frame");
61     //cv::destroyWindow("Modified Frame");
62     frame_Modified.release();

63
64     /*Device*/
65     cudaFree(Image_dev);
66
67     return(0);
68 }
```



MODIFICAR IMAGEN A COLOR (C3)

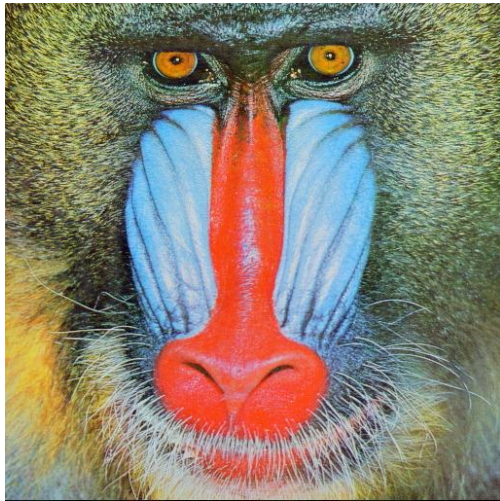
```
ModificarlImagen.h* x ModificarlImagen.cpp ModificarlImagen.cu
Miscellaneous Files (Global Scope)
1
2 void CUDA_Modificar_Imagen(uchar3 *Image_dev,int N,dim3 grid,dim3 threads);
```

```
ModificarlImagen.h* ModificarlImagen.cpp ModificarlImagen.cu* x
Miscellaneous Files (Global Scope)
1
2 #include "ModificarlImagen.h"
3 // Kernel Function which is executed in the Device.
4 __global__ void Modificar_Imagen(uchar3 *Imag,int N)
5 {
6     int idx = blockIdx.x * blockDim.x + threadIdx.x;
7
8     if (idx<N){
9         if((Imag[idx].x+Imag[idx].y+Imag[idx].z)/3 > 250){
10             Imag[idx].x=255; //B
11             Imag[idx].y=0; //G
12             Imag[idx].z=0; //R
13         }
14     }
15 }
16 void CUDA_Modificar_Imagen(uchar3 *Image_dev,int N,dim3 grid,dim3 threads){
17     Modificar_Imagen<<<grid,threads>>> (Image_dev,N);
18 }
```

Para compilar:

```
nvcc `pkg-config --cflags opencv4` ModificarlImagen.cu ModificarlImagen.cpp -o ModificarlImagen
`pkg-config --libs opencv4`
```

COMPOSICIÓN DE IMÁGENES



αI_1

+



$(1 - \alpha)I_2$

=



0 con $\alpha = 0.5$

COMPOSICIÓN DE IMÁGENES (C1)

```
3 | #include <stdio.h>
4 | /*CUDA*/
5 | #include <cuda_runtime.h>
6 | /*OpenCV*/
7 | #include <opencv2/highgui/highgui.hpp>
8 | #include "ImageComposition.h"
9 |
10 | //alpha parameter
11 | int alpha_int=75;
12 | float alpha= (float)alpha_int / 100; //[0,1]
13 | void Change_alpha(int,void *){
14 |     alpha=(float)alpha_int/100;
15 | }
16 |
17 | int main(int argc, char **argv){
18 |     cudaSetDevice(0);
19 |     /*Host Variables*/
20 |     int imageW, imageH;           //Size of Image
21 |     cv::Mat frame1_Original;     //Original Image
22 |     cv::Mat frame2_Original;     //Original Image
23 |     cv::Mat frame_Composed;
```

COMPOSICIÓN DE IMÁGENES (C2)

```
25     /*Device Variables*/
26     uchar3 *Image1_dev,*Image2_dev,*ComposedImage_dev;
27
28     /*cv::namedWindow("Original Frame1",CV_WINDOW_AUTOSIZE);
29     cv::namedWindow("Original Frame2",CV_WINDOW_AUTOSIZE);
30     cv::namedWindow("Composed Frame",CV_WINDOW_AUTOSIZE);
31     cv::createTrackbar("alpha", "Composed Frame",&alpha_int,100,Change_alpha,0);*/
32
33     char name_imag[500];
34     /*Load Image*/
35     sprintf(name_imag,"../images/baboon.jpg");
36     frame1_Original = cv::imread(name_imag,1);
37
38     sprintf(name_imag,"../images/lena.jpg");
39     frame2_Original = cv::imread(name_imag,1);
40
41     /*Size of Image*/
42     imageW=frame1_Original.cols;
43     imageH=frame1_Original.rows;
44     size_t size=imageW*imageH*sizeof(uchar3);
```

COMPOSICIÓN DE IMÁGENES (C3)

```
46     /*Create host memory*/
47     frame_Composed.create(imageH,imageW,CV_8UC(3));
48
49     /*Create device memory*/
50     cudaMalloc((void **)&Image1_dev,size);
51     cudaMalloc((void **)&Image2_dev,size);
52     cudaMalloc((void **)&ComposedImage_dev,size);
53
54     /*Copy Memory (Host-->Device)*/
55     cudaMemcpy(Image1_dev,frame1_Original.data,size,/*Complete*/);
56     cudaMemcpy(Image2_dev,frame2_Original.data,size,/*Complete*/);
57
58     /*Define the size of the grid and thread blocks*/
59     dim3 threads(/*Complete*/,1,1);
60     int N=imageW * imageH;
61     dim3 grid(N/threads.x + (N%threads.x == 0 ? 0:1),1,1);
62
63     /*cv::imshow("Original Frame1",frame1_Original);
64     cv::imshow("Original Frame2",frame2_Original);*/
```

COMPOSICIÓN DE IMÁGENES (C4)

```
66 //while(1){
67     /*Launch the Kernel Function*/
68     CUDA_Compose_Images(ComposedImage_dev,Image1_dev,Image2_dev,alpha,N,grid,threads);
69
70     /*Copy Memory (Device-->Host)*/
71     cudaMemcpy(frame_Composed.data,ComposedImage_dev,size,/*Complete*/);
72
73     //cv::imshow("Composed Frame",frame_Composed);
74
75     /* char key=cvWaitKey(2);
76        if(key==27) {
77            break;
78        }
79    */
80
81     //Save the result
82     cv::imwrite("../results/Compose_babon_lena.jpg", /*Complete*/);
83
84     /*Clean Memory*/
85     /*Host*/
86     /*cv::destroyAllWindows();*/
87     frame_Composed.release();
88     /*Device*/
89     cudaFree(Image1_dev);
90     cudaFree(Image2_dev);
91     cudaFree(ComposedImage_dev);
92
93     return(0);
94 }
```

COMPOSICIÓN DE IMÁGENES (C5)

```
ImageComposition.h*  ImageComposition.cpp  ImageComposition.cu
Miscellaneous Files  (Global Scope)
1
2 void CUDA_Compose_Images(uchar3 *ComposedImage_dev,uchar3 *Image1_dev,uchar3 *Image2_dev,
3 float alpha,int N,dim3 grid,dim3 threads);
```

```
ImageComposition.h  ImageComposition.cpp  ImageComposition.cu  X
1 #include "ImageComposition.h"
2
3 __global__ void Compose_Images(uchar3 *ComposedImage_dev,uchar3 *Image1_dev,uchar3 *Image2_dev,
4 float alpha,int N){
5 int idx = blockIdx.x * blockDim.x + threadIdx.x;
6 if (/*Complete*/){
7 ComposedImage_dev[idx].x=alpha/*Complete*/+(1-alpha)/*Complete*/;
8 ComposedImage_dev[idx].y=alpha/*Complete*/+(1-alpha)/*Complete*/;
9 ComposedImage_dev[idx].z=alpha/*Complete*/+(1-alpha)/*Complete*/;
10 }
11 }
12
13 void CUDA_Compose_Images(uchar3 *ComposedImage_dev,uchar3 *Image1_dev,uchar3 *Image2_dev,
14 float alpha,int N,dim3 grid,dim3 threads){
15 Compose_Images<<</*Complete*/>>>(ComposedImage_dev,Image1_dev,Image2_dev,alpha,N);
16 }
```

APLICAR FILTROS A UNA IMÁGEN



I_Original

$$\otimes \frac{1}{49} \begin{pmatrix} 1 & \dots & 1 \\ \vdots & \ddots & \vdots \\ 1 & \dots & 1 \end{pmatrix}_{7 \times 7} =$$

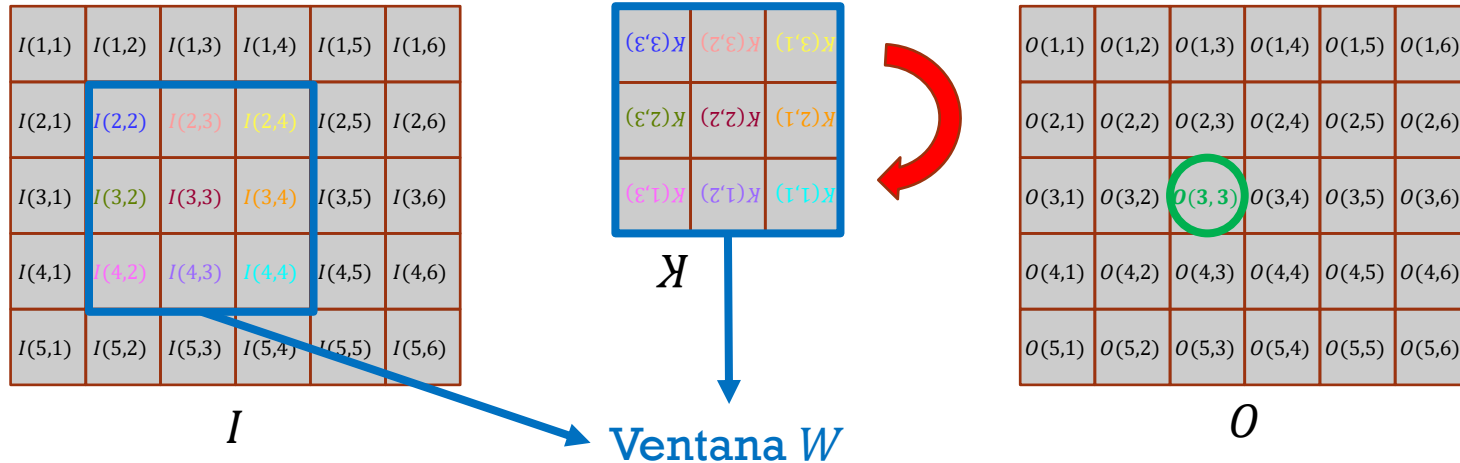
Kernel de convolución
o correlación



I_Filtrada

CONVOLUCIÓN

correlación con kernel girado



$$O(3,3) = I(4,4) * K(1,1) + I(4,3) * K(1,2) + I(4,2) * K(1,3) + I(3,4) * K(2,1) + I(3,3) * K(2,2) + I(3,2) * K(2,3) + I(2,4) * K(3,1) + I(2,3) * K(3,2) + I(2,2) * K(3,3)$$

filter2D

Convolve an image with the kernel.

C++: `void filter2D(InputArray src, OutputArray dst, int ddepth, InputArray kernel, Point anchor=Point(-1,-1), double delta=0, int borderType=BORDER_DEFAULT)`

OpenCV: https://docs.opencv.org/3.4.1/d4/d86/group__imgproc__filter.html

FILTROS: PROMEDIO, GAUSSIANO Y LAPLACIANO

```
3  #include <stdio.h>
4  /*CUDA*/
5  #include <cuda_runtime.h>
6  /*OpenCV*/
7  #include <opencv2/opencv.hpp>
8
9  #include "ImageFilters.h"
10
11 //División techo.
12 int iDivUp(int a, int b){
13     return ((a % b) != 0) ?
14         (a / b + 1) : (a / b);
15 }
16
17 //PARAMETERS
18 #define BLOCKDIM_X 16
19 #define BLOCKDIM_Y 16
20
21 int main(int argc, char **argv){
22     /*Host Variables*/
23     int imageW, imageH; //Size of Image
24     cv::Mat I_Original; //Original Image
25     cv::Mat I_Filtrada; //Para guardar el resultado
26     cv::Mat I Filtrada C1F; //Imagen de 1 Canal en Float
```

$$K_{Promedio} = \frac{1}{tW \times tW} \begin{pmatrix} 1 & \dots & 1 \\ \vdots & \ddots & \vdots \\ 1 & \dots & 1 \end{pmatrix}_{tW \times tW}$$

$$K_{Gaussiano} = \frac{1}{16} \begin{pmatrix} 1 & 2 & 1 \\ 2 & 4 & 2 \\ 1 & 2 & 1 \end{pmatrix}$$

$$K_{Laplaciano} = \begin{pmatrix} 0 & 1 & 0 \\ 1 & -4 & 1 \\ 0 & 1 & 0 \end{pmatrix}$$

FILTROS: PROMEDIO, GAUSSIANO Y LAPLACIANO (C1)

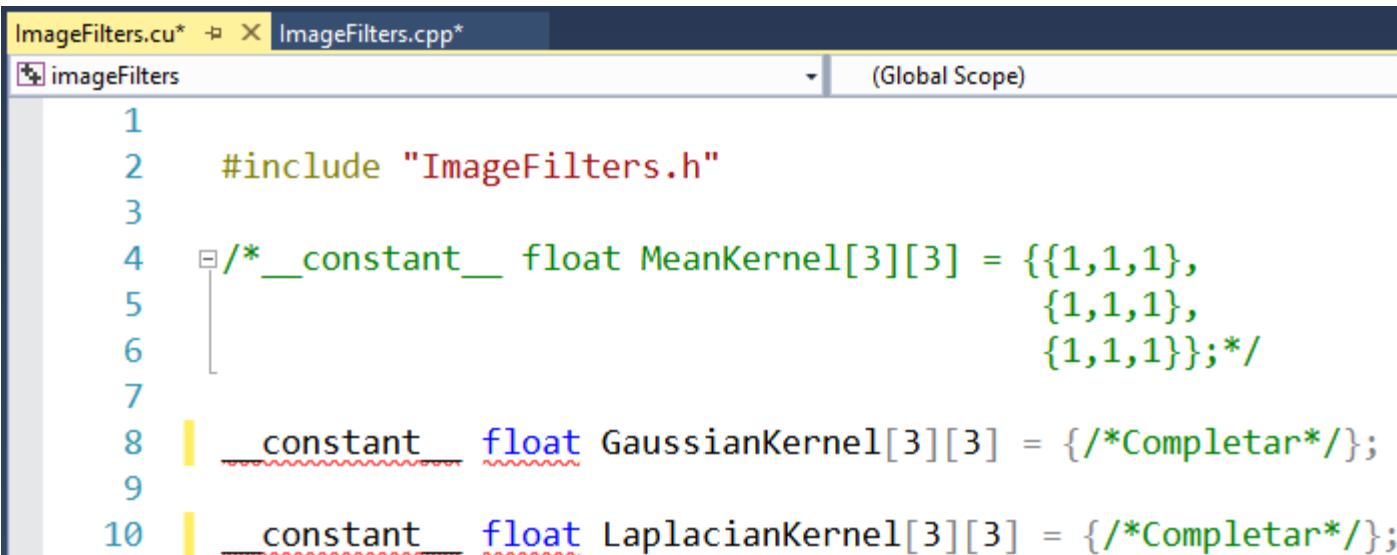
```
27     /*Device Variables*/
28     unsigned char *I_Original_dev;
29     unsigned char *I_Filtrada_dev;
30     float *I_Filtrada_C1F_dev;
31
32     char name_imag[500];
33     /*Load Image*/
34     sprintf(name_imag, /*Completar*/);
35     I_Original = cv::imread(name_imag,0);
36
37     /*Size of Image*/
38     imageW=I_Original.cols;
39     imageH=I_Original.rows;
40     size_t size=imageW*imageH*sizeof(unsigned char);
41     size_t sizef=imageW*imageH*sizeof(float);
42
43     I_Filtrada.create(imageH, imageW, CV_8UC(1));
44     I_Filtrada_C1F.create(imageH, imageW, CV_32FC(1));
45
46     /*Create device memory*/
47     cudaMalloc((void **)&I_Original_dev, size);
48     cudaMalloc((void **)&I_Filtrada_dev,size);
49     cudaMalloc((void **)&I_Filtrada_C1F_dev,sizef);
50     cudaMemset(I_Filtrada_dev, 0, size); //Inicializamos en cero
51     cudaMemset(I_Filtrada_C1F_dev, 0, sizef);
```

FILTROS: PROMEDIO, GAUSSIANO Y LAPLACIANO (C2)

```
54     /*Copy Memory (Host-->Device)*/
55     cudaMemcpy(I_Original_dev,I_Original.data,size,/*Completar*/);
56
57     /*Define the size of the grid and thread blocks*/
58     dim3 threads(/*Completar*/);
59     dim3 grid(iDivUp(imageW, /*Completar*/), iDivUp(imageH, /*Completar*/),1);
61     /*Launch the Kernel Function*/
62     //Mean Filter
63     CUDA_MeanFilter(I_Filtrada_dev, I_Original_dev,imageW,imageH,grid,threads);
64     //CUDA_GaussianFilter(I_Filtrada_dev, I_Original_dev,imageW,imageH,grid,threads);
65     //CUDA_LaplacianFilter(I_Filtrada_C1F_dev,I_Original_dev,imageW,imageH,grid,threads);
67     /*Copy Memory (Device-->Host)*/
68     cudaMemcpy(I_Filtrada.data, I_Filtrada_dev, size, /*Completar*/);
69     //cudaMemcpy(I_Filtrada_C1F.data, I_Filtrada_C1F_dev,sizef,/*Completar*/);
71     cv::imshow("Imagen Original", I_Original);
72     cv::imshow("Imagen Filtrada", I_Filtrada);
73     /*cv::normalize(I_Filtrada_C1F, I_Filtrada_C1F, 1, 0, CV_MINMAX);
74     cv::imshow("Imagen Filtrada", I_Filtrada_C1F);*/
75     cv::waitKey(0);
77     cv::imwrite("../..//images/lena_MeanFilter.png", I_Filtrada);
78     //cv::imwrite("../..//images/lena_GaussianFilter.png", I_Filtrada);
79     /*cv::normalize(I_Filtrada_C1F, I_Filtrada_C1F, 255, 0, CV_MINMAX);
80     cv::imwrite("../..//images/lena_LaplacianFilter.png", I_Filtrada_C1F);*/
```

FILTROS: PROMEDIO, GAUSSIANO Y LAPLACIANO (C3)

```
82     /*Clean Memory*/
83     /*Host*/
84     I_Filtrada.release();
85     I_Filtrada_C1F.release();
86     //cv::destroyAllWindows();
87     /*Device*/
88     cudaFree(I_Original_dev);
89     cudaFree(I_Filtrada_dev);
90     cudaFree(I_Filtrada_C1F_dev);
91
92     return(0);
93 }
```



```
ImageFilters.cu* x ImageFilters.cpp*
imageFilters (Global Scope)
1
2     #include "ImageFilters.h"
3
4     /*__constant__ float MeanKernel[3][3] = {{1,1,1},
5                                             {1,1,1},
6                                             {1,1,1}};*/
7
8     constant float GaussianKernel[3][3] = {/*Completar*/};
9
10    constant float LaplacianKernel[3][3] = {/*Completar*/};
```

FILTRO PROMEDIO

```
12  /*Image Filters*/
13  global void MeanFilter_kernel(unsigned char *Dst_dev, unsigned char *Src_dev,
14                                     int imageW,int imageH){
15
16      const int ix = blockDim.x * blockIdx.x + threadIdx.x;
17      const int iy = blockDim.y * blockIdx.y + threadIdx.y;
18
19      int rW = 3;//radio de la ventana
20      int tW = rW * 2+1;
21      if(ix>=rW && ix < imageW-rW && iy>=rW && iy < imageH-rW){//Dejamos un margen de tamaño rW
22          float sum=0;
23          int idx;
24          for(int k_i=0;k_i<tW;k_i++){//Para recorrer el Kernel en cada pixel (iy,ix)
25              idx = (iy + (k_i - rW))*imageW + ix;
26              for(int k_j=0;k_j<tW;k_j++){
27                  sum+=(float)Src_dev[idx + (k_j - rW)];
28                  /*sum+=(float)Src_dev[idx + (k_j - rW)]*MeanKernel[k_i][k_j];*/
29              }
30          }
31          idx = iy*imageW + ix;
32          Dst_dev[idx]=(unsigned char)(sum/(tW*tW));
33      }
34 }
```

FILTRO GAUSSIANO

```
33 __global__ void GaussianFilter_kernel(unsigned char *Dst_dev, unsigned char *Src_dev,
34                                     int imageW, int imageH) {
35
36     const int ix = blockDim.x * blockIdx.x + threadIdx.x;
37     const int iy = blockDim.y * blockIdx.y + threadIdx.y;
38
39     if (ix > 0 && ix < imageW - 1 && iy > 0 && iy < imageH - 1) { //Dejamos un margen de tamaño 1
40         float sum = 0;
41         int idx;
42         for (int k_i = 0; k_i < 3; k_i++) { //Para recorrer el Kernel en cada pixel (iy,ix)
43             idx = (iy + (k_i - 1)) * imageW + ix;
44             for (int k_j = 0; k_j < 3; k_j++) {
45                 sum += (float)Src_dev[idx + (k_j - 1)] * /*Completar*/;
46             }
47         }
48         idx = iy * imageW + ix;
49         Dst_dev[idx] = (unsigned char)(sum / 16);
50     }
51 }
```

FILTRO LAPLACIANO

```
56 __global__ void LaplacianFilter_kernel(float *Dst_dev, unsigned char *Src_dev,  
57                                     int imageW, int imageH){  
58  
59     const int ix = blockDim.x * blockIdx.x + threadIdx.x;  
60     const int iy = blockDim.y * blockIdx.y + threadIdx.y;  
61  
62     if (ix >0 && ix < imageW - 1 && iy >0 && iy < imageH - 1) {//Dejamos un margen de tamaño 1  
63         float sum = 0;  
64         int idx;  
65  
66         /*Completar*/  
67  
68         idx = iy*imageW + ix;  
69         Dst_dev[idx] = sum;  
70     }  
71 }
```

FILTROS: PROMEDIO, GAUSSIANO Y LAPLACIANO (C4)

ImageFilters.h ImageFilters.cu* ImageFilters.cpp

```
73 void CUDA_MeanFilter(unsigned char *Dst_dev, unsigned char *Src_dev,int imageW,int imageH,  
74                     dim3 grid,dim3 threads){  
75     MeanFilter_kernel/*Completar*/(Dst_dev,Src_dev,imageW,imageH);  
76 }  
77  
78 void CUDA_GaussianFilter(unsigned char *Dst_dev, unsigned char *Src_dev, int imageW, int imageH,  
79                          dim3 grid, dim3 threads) {  
80     GaussianFilter_kernel/*Completar*/(Dst_dev, Src_dev, imageW, imageH);  
81 }  
82  
83 void CUDA_LaplacianFilter(float *Dst_dev, unsigned char *Src_dev,int imageW,int imageH,  
84                          dim3 grid,dim3 threads){  
85     LaplacianFilter_kernel/*Completar*/(Dst_dev, Src_dev,imageW,imageH);  
86 }
```

ImageFilters.h* ImageFilters.cu* ImageFilters.cpp

```
4 void CUDA_MeanFilter(unsigned char *Dst_dev,unsigned char *Src_dev,int imageW,int imageH,  
5                     dim3 grid,dim3 threads);  
6  
7 void CUDA_GaussianFilter(unsigned char *Dst_dev, unsigned char *Src_dev, int imageW, int imageH,  
8                          dim3 grid, dim3 threads);  
9  
10 void CUDA_LaplacianFilter(float *Dst_dev, unsigned char *Src_dev, int imageW, int imageH,  
11                          dim3 grid, dim3 threads);
```

RESULTADOS



I_Original



I_Filtrada, $K_{promedio}$



I_Filtrada, $K_{Gaussiano}$



I_Filtrada, $K_{Laplaciano}$

GRACIAS POR SU ATENCIÓN

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